

$$T: V \times V \rightarrow \mathbb{R}$$

$$T(e_i, e_j) = T_{ij} \Leftrightarrow T = \sum_{i,j} T_{ij} e^i \otimes e^j$$

$$e^i(e_j) = \delta_{ij}$$

$$S: V \times V \rightarrow V$$

$$S(e_i, e_j) = \sum_k S_{ij}^k e_k$$

$$S = \sum_{i,j,k} S_{ij}^k e^i \otimes e^j \otimes e_k$$

(Some authors:  
 $S = \sum_{i,j,k} S_{ij}^k e_k \otimes e^i \otimes e^j$ )

$$\det: \underbrace{\mathbb{R}^n \times \dots \times \mathbb{R}^n}_{n \text{ times}} \rightarrow \mathbb{R}$$

$$\det \begin{bmatrix} 0 & 0 & \dots & 0 \end{bmatrix}$$

$$\underline{n=2}: \det(e_1, e_1) = 0$$

$$\det(e_1, e_2) = \det \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 1$$

$$\det(e_2, e_1) = -1$$

$$\det(e_2, e_2) = 0.$$

$$\det = e^1 \otimes e^2 - e^2 \otimes e^1 = dx \otimes dy - dy \otimes dx.$$

$$\mathbb{R}^2(x, y)$$

cross product.

$$\mu: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}^3, \quad \mu(v, w) := v \times w$$

$$\mu(e_1, e_1) = 0$$

$$\mu(e_1, e_2) = e_3$$

$$\mu(e_1, e_3) = -e_2$$

$$\mu(e_2, e_1) = -e_3$$

$$\mu(e_2, e_2) = 0$$

$$\mu(e_2, e_3) = e_1$$

$$\mu(e_3, e_1) = e_2$$

$$\mu(e_3, e_2) = -e_1$$

$$\mu(e_3, e_3) = 0$$

$$\begin{aligned} \mu = & e^1 \otimes e^2 \otimes e_3 - e^2 \otimes e^1 \otimes e_3 \\ & + e^2 \otimes e^3 \otimes e_1 - e^3 \otimes e^2 \otimes e_1 \\ & + e^3 \otimes e^1 \otimes e_2 - e^1 \otimes e^3 \otimes e_2. \end{aligned}$$

$$T, S \in V^*$$

$$T \wedge S := T \otimes S - S \otimes T, \quad S \wedge T = S \otimes T - T \otimes S = -T \wedge S.$$



$$\det: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}, \quad \det = e^1 \wedge e^2 = dx \wedge dy.$$

$$\mu = (e^1 \wedge e^2) \otimes e_3 + (e^2 \wedge e^3) \otimes e_1 + (e^3 \wedge e^1) \otimes e_2.$$

$$\text{span}\{e_i\} = V, \quad \text{span}\{e^i\} = V^*.$$

$$\boxed{e^i \wedge e^i = 0}$$

$$T_1, T_2, T_3 \in V^*$$

WANT:  $T_1 \wedge T_2 \wedge T_3 =$  linear combinations of  $T_i \otimes T_j \otimes T_k$ .

such swapping any pair of  $\{T_1, T_2, T_3\}$  in  $T_1 \wedge T_2 \wedge T_3$  gives  $(-ve)$ .

$$\begin{aligned} \text{e.g. } T_1 \wedge T_2 \wedge T_3 &= -T_2 \wedge T_1 \wedge T_3 = -T_1 \wedge T_3 \wedge T_2 \\ &= -T_3 \wedge T_2 \wedge T_1 \end{aligned}$$

input  $\rightarrow \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} : \{1, 2, 3\} \rightarrow \{1, 2, 3\}$

output  $\rightarrow$          

        "        

(123)

        1  $\mapsto$  2

        2  $\mapsto$  3

        3  $\mapsto$  1

$$(12) = \begin{pmatrix} 1 & 2 & 3 & 4 & \dots & n \\ 2 & 1 & 3 & 4 & \dots & n \end{pmatrix}$$

transposition.

$$(123) = (12)(23)$$

$$(132) = (13)(32)$$

### Theorem 3.29

$\forall \sigma \in S_n \leftarrow n$ -th permutation group,

$\exists \tau_1, \dots, \tau_k$  transpositions s.t.

$$(12)(12) = \text{id.}$$

$$\sigma = \tau_1 \circ \tau_2 \circ \dots \circ \tau_k$$

and  $(-1)^k$  is uniquely determined.

"  
sign( $\sigma$ )

sgn

$$T_1 \wedge \dots \wedge T_k \quad T_i \in V^* = \text{span}\{e^i\}_{i=1}^n$$

$$:= \sum_{\sigma \in S_k} \text{sgn}(\sigma) T_{\sigma(1)} \otimes T_{\sigma(2)} \otimes \dots \otimes T_{\sigma(k)}$$

Claim:  $\tau$  transposition in  $S_k$ ,

then  $T_{\tau(1)} \wedge T_{\tau(2)} \wedge \dots \wedge T_{\tau(k)}$

$$= -T_1 \wedge T_2 \wedge \dots \wedge T_k.$$

Proof:  $T_{\tau(1)} \wedge T_{\tau(2)} \wedge \dots \wedge T_{\tau(k)}$

$$= \sum_{\sigma \in S_k} \text{sgn}(\sigma) T_{\underbrace{\sigma(\tau(1))}_{\sigma \circ \tau(1)}} \otimes T_{\underbrace{\sigma(\tau(2))}_{\sigma \circ \tau(2)}} \otimes \dots \otimes T_{\underbrace{\sigma(\tau(k))}_{\sigma \circ \tau(k)}}$$

bijective.

$$\sigma \mapsto \underbrace{\sigma \circ \tau}_{\sigma'} \quad \sigma' = \sigma \circ \tau \Leftrightarrow \sigma = \sigma' \circ \tau$$

$$= \sum_{\sigma' \in S_k} \underbrace{\text{sgn}(\sigma' \circ \tau)}_{-\text{sgn}(\sigma')} T_{\sigma'(1)} \otimes T_{\sigma'(2)} \otimes \dots \otimes T_{\sigma'(k)}$$

$$= - \sum_{\sigma' \in S_k} \text{sgn}(\sigma') T_{\sigma'(1)} \otimes T_{\sigma'(2)} \otimes \dots \otimes T_{\sigma'(k)}$$

$$= - T_1 \wedge T_2 \wedge \dots \wedge T_k.$$

$$(T_1 \wedge T_2) \wedge (T_3 \wedge T_4 \wedge T_5) := T_1 \wedge T_2 \wedge T_3 \wedge T_4 \wedge T_5.$$

$$\begin{aligned} (-T_2 \wedge T_1) \wedge (T_3 \wedge T_4 \wedge T_5) &= -T_2 \wedge T_1 \wedge T_3 \wedge T_4 \wedge T_5 \\ &= T_1 \wedge T_2 \wedge T_3 \wedge T_4 \wedge T_5. \end{aligned}$$

Prop:

$$\omega \in \Lambda^k(V^*) := \text{span} \left\{ e^{i_1} \wedge \dots \wedge e^{i_k} \right\}_{\substack{\dim V \\ i_1, \dots, i_k=1}}$$

$$\eta \in \Lambda^l(V^*)$$

$$\text{then } \omega \wedge \eta = (-1)^{kl} \eta \wedge \omega.$$

Proof:  $(e^{i_1} \wedge \dots \wedge e^{i_k}) \wedge (e^{j_1} \wedge \dots \wedge e^{j_l})$

↖  $k$ -times ↗  
↖  $k$ -times ↗

Total:  $kl$  times :

$$(-1)^{kl}$$



$$e^i \wedge e^i = 0.$$

$\omega \in \Lambda^2(V^*)$ ,  $\omega \wedge \omega$  is not necessarily 0.

$$\omega = e^1 \wedge e^2 + e^3 \wedge e^4 \quad \text{in } \mathbb{R}^4$$

$$\begin{aligned} \omega \wedge \omega &= (e^1 \wedge e^2 + e^3 \wedge e^4) \wedge (e^1 \wedge e^2 + e^3 \wedge e^4) \\ &= e^1 \wedge e^2 \wedge e^3 \wedge e^4 + \underbrace{e^3 \wedge e^4 \wedge e^1 \wedge e^2}_{= e^1 \wedge e^2 \wedge e^3 \wedge e^4} \\ &= 2e^1 \wedge e^2 \wedge e^3 \wedge e^4 \neq 0. \end{aligned}$$

$$\begin{aligned} \eta \in \Lambda^3(V^*), \quad \eta \wedge \eta &= (-1)^{3 \times 3} \eta \wedge \eta = -\eta \wedge \eta. \\ \Rightarrow \eta \wedge \eta &= 0 \quad (\text{char } \mathbb{R} \neq 2). \end{aligned}$$

$$\forall i=1, 2, \dots, n:$$

$$\omega^i := \sum_{j=1}^n a_j^i e^j$$

$$V = \text{span}\{e_i\}_{i=1}^n$$

$$V^* = \text{span}\{e^j\}_{j=1}^n$$

$$\omega^1 \wedge \dots \wedge \omega^n$$

$$= \left( \sum_{j_1=1}^n a_{j_1}^1 e^{j_1} \right) \wedge \left( \sum_{j_2=1}^n a_{j_2}^2 e^{j_2} \right) \wedge \dots \wedge \left( \sum_{j_n=1}^n a_{j_n}^n e^{j_n} \right)$$

$$= \sum_{\substack{j_1, \dots, j_n=1 \\ \text{distinct}}}^n a_{j_1}^1 a_{j_2}^2 \dots a_{j_n}^n e^{j_1} \wedge e^{j_2} \wedge \dots \wedge e^{j_n}$$

$$= \sum_{j \in S_n} a_{j(1)}^1 a_{j(2)}^2 \dots a_{j(n)}^n \underbrace{e^{j(1)} \wedge e^{j(2)} \wedge \dots \wedge e^{j(n)}}_{\text{sgn}(j) e^1 \wedge \dots \wedge e^n}$$

$$= \left( \sum_{j \in S_n} \text{sgn}(j) a_{j(1)}^1 a_{j(2)}^2 \dots a_{j(n)}^n \right) e^1 \wedge \dots \wedge e^n$$

$$\det [a_j^i]$$

$$\omega^1 \wedge \dots \wedge \omega^n = \det [a_j^i] e^1 \wedge \dots \wedge e^n.$$

$$T_p^* M = \text{span} \{ du^i|_p \}_{i=1}^n = \text{span} \{ dv^\alpha|_p \}_{\alpha=1}^n$$

$$du^i = \sum_{\alpha=1}^n \frac{\partial u_i}{\partial v_\alpha} dv^\alpha$$

$$du^1 \wedge du^2 \wedge \dots \wedge du^n = \det \left[ \frac{\partial u_i}{\partial v_\alpha} \right] dv^1 \wedge \dots \wedge dv^n.$$

$$\left\{ \begin{array}{l} du^1 \wedge \dots \wedge du^n = \det \frac{\partial (u_1, \dots, u_n)}{\partial (v_1, \dots, v_n)} dv^1 \wedge \dots \wedge dv^n \end{array} \right\}$$

c.f. change of coordinates formula in 2023.

$$dx = \frac{\partial x}{\partial r} dr + \frac{\partial x}{\partial \theta} d\theta$$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$= \cos \theta dr - r \sin \theta d\theta$$

$$dy = \sin \theta dr + r \cos \theta d\theta$$

$$dx \wedge dy = (\cos \theta dr - r \sin \theta d\theta) \wedge (\sin \theta dr + r \cos \theta d\theta)$$

$$= r \cos^2 \theta \underbrace{dr \wedge d\theta} - r \sin^2 \theta \underbrace{d\theta \wedge dr}$$

$$= \underline{r \cos^2 \theta} dr \wedge d\theta + \underline{r \sin^2 \theta} dr \wedge d\theta$$

$$= r dr \wedge d\theta.$$

### § 3.5 Exterior derivatives.

$$f: M \rightarrow \mathbb{R}$$

$$df := \sum_{i=1}^n \frac{\partial f}{\partial u_i} du^i$$

Verify  $\rightarrow$  indep. of local coordinates.

$$\sum_{i=1}^n \frac{\partial f}{\partial u_i} du^i = \sum_{i, \alpha, \beta} \frac{\partial f}{\partial v_\alpha} \frac{\partial v_\alpha}{\partial u_i} \frac{\partial u^i}{\partial v_\beta} dv^\beta$$

$$= \sum_{\alpha, \beta} \frac{\partial f}{\partial v_\alpha} \underbrace{\frac{\partial v_\alpha}{\partial v_\beta}}_{\delta_{\alpha\beta}} dv^\beta = \sum_{\alpha} \frac{\partial f}{\partial v_\alpha} dv^\alpha$$

Exercise:  $\sum_{i=1}^n \frac{\partial f}{\partial u_i} \frac{\partial}{\partial u_i}$  is not indep. of local coordinates.