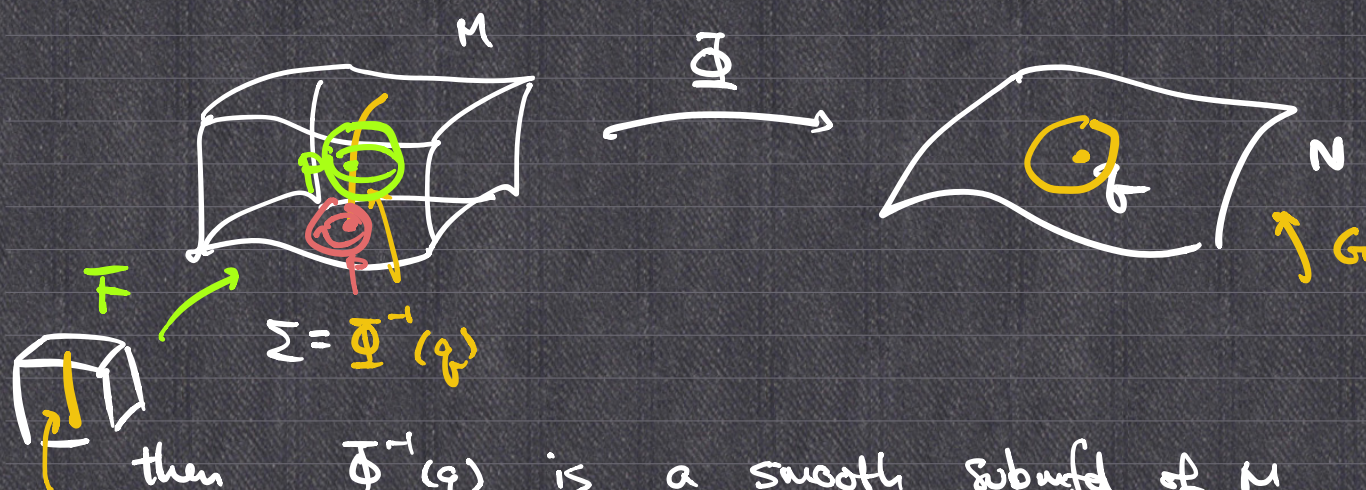


$\Phi: M \rightarrow N$ is a submersion on $\Sigma = \Phi^{-1}(q)$



then $\Phi^{-1}(q)$ is a smooth submanifold of M
 $(0, \dots, 0, u_{n+1}, \dots, u_m)$ and $\dim \Phi^{-1}(q) = \dim M - \dim N$.

Recall Submersion Theorem

$$\Rightarrow \exists F(u_1, \dots, u_m) : u \rightarrow \overset{\rightarrow p}{\mathcal{O}} \subset M$$

$$G(v_1, \dots, v_n) : \tilde{u} \rightarrow \mathcal{O} \subset N$$

$\exists \Phi(p) = q$

s.t.

$$G^{-1} \circ \Phi \circ F(u_1, \dots, u_m) = (u_1, \dots, u_n)$$

$$\tilde{F}(u_{n+1}, \dots, u_m) := F(0, \dots, 0, \overset{\uparrow u_n}{u_{n+1}}, \dots, u_m)$$

parametrizes Σ near p .

Exercise: $\tilde{F}_1^{-1} \circ \tilde{F}_2 = F_1^{-1} \circ F_2 \big|_{\{0\} \times \mathbb{R}^{(m-n)}}$

$\therefore \Sigma$ is a smooth manifold with
 $\dim = m - n$.

$i: \Sigma \rightarrow M$ inclusion.

$$\begin{array}{ccc} \tilde{F} & \uparrow & \uparrow F \\ & \tilde{F} \circ L \circ \tilde{F} & \\ & \xrightarrow{\quad} & \end{array}$$

$$F^{-1} \circ L \circ \tilde{F}(u_{n+1}, \dots, u_m) = F^{-1} \circ \cancel{L}(F(0, \dots, 0, u_{n+1}, \dots, u_m)) \\ = (0, \dots, 0, u_{n+1}, \dots, u_m)$$

$$D(F^{-1} \circ L \circ \tilde{F}) = \begin{bmatrix} 0 \\ I \end{bmatrix}$$

cols are linearly indep.

$\therefore L$ is an immersion.

$\Sigma \subset M$ is a C^0 submfd of M .



Chapter 3

V = finite dim'l vector space / $\mathbb{R}$.
 $= \text{span} \{e_i\}_{i=1}^n$

V^* = set of linear maps from V to $\mathbb{R}$.
 $= \mathcal{L}(V, \mathbb{R}) = \text{Hom}(V, \mathbb{R}). \quad (\dim V^* = \dim V)$

$l \in V^*, \quad l: V \rightarrow \mathbb{R}. \quad l(e_i) \in \mathbb{R}.$

$$e^i \in V^*, e^i: V \rightarrow \mathbb{R}$$

$$e^i(e_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases} = \delta_{ij}$$

Exercise: $\{e^i\}_{i=1}^n$ are linearly indep.

↑
dual basis of V^* wrt. $\{e_i\}_{i=1}^n$.

$$l \in V^*, \quad l(e_i) = a_i \quad \forall i=1,2,\dots,n.$$

$$\text{Then: } l = \sum_{i=1}^n a_i e^i$$

$$l(e_j) = \sum_{i=1}^n a_i e^i(e_j) = \sum_{i=1}^n a_i \delta_{ij} = a_j.$$

$$\therefore l(e_i) = a_i \in \mathbb{R} \Leftrightarrow l = \sum_{i=1}^n a_i e^i$$

bra ket.

$$\langle e_i | \quad | e_j \rangle.$$

$$\langle e_i | e_j \rangle = \delta_{ij}$$

$$\langle T | e_j \rangle = a_j$$

$$\Leftrightarrow \langle T | = \sum_i a_i \langle e_i |.$$

$$l \in V^*$$

$$V = \mathbb{R}^3 = \text{span}\{e_1, e_2, e_3\}$$

$$\begin{cases} l(e_1) = 3 \\ l(e_2) = 2 \\ l(e_3) = -5 \end{cases} \Leftrightarrow l = 3e^1 + 2e^2 - 5e^3.$$

$$T_p M = \text{span} \left\{ \frac{\partial}{\partial u_i} (p) \right\}$$

$$F(u_1, \dots, u_n): U \xrightarrow{p} \text{OCM}.$$

$$\underbrace{T_p^* M := (T_p M)^*}$$

↑ cotangent space at p .

Denote $\{du^i|_p\}_{i=1}^n$ to be the dual basis of $T_p^* M$ wrt $\{\frac{\partial}{\partial u_i}(p)\}_{i=1}^n$

$$du^i|_p: T_p M \rightarrow \mathbb{R}.$$

$$du^i|_p \left(\frac{\partial}{\partial u_j} (p) \right) := \delta_{ij}$$

$$\alpha \in T_p^* M, \quad \alpha: T_p M \rightarrow \mathbb{R}.$$

$$\alpha \left(\frac{\partial}{\partial u_i} \right) = c_i \quad \forall i$$

$$\alpha = \sum_{i=1}^n c_i du^i$$

$$\begin{array}{l} M \\ F(u_1, \dots, u_n) \end{array} \rightarrow \text{span} \left\{ \frac{\partial}{\partial u_i} (p) \right\} = T_p M \rightarrow \text{span} \{ du^i|_p \} = T_p^* M$$

$$G(v_1, \dots, v_n)$$

$$\rightarrow \text{span} \left\{ \frac{\partial}{\partial u_j} (p) \right\} = T_p M \rightarrow \text{span} \{ dv^j|_p \} = T_p^* M$$

$$\frac{\partial}{\partial u_i} = \sum_j \frac{\partial v_j}{\partial u_i} \frac{\partial}{\partial v_j}$$

$$du^i \left(\frac{\partial}{\partial v_j} \right) = du^i \left(\sum_k \frac{\partial u_k}{\partial v_j} \frac{\partial}{\partial u_k} \right)$$

$$= \sum_k \frac{\partial u_k}{\partial v_j} \delta_{ik} = \frac{\partial u_i}{\partial v_j}$$

$$\Rightarrow du^i = \sum_j \frac{\partial u_i}{\partial v_j} dv^j \quad \leftarrow$$

e.g. $\mathbb{R}^2$ (x, y) , (r, θ)

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$\begin{cases} dx = \frac{\partial x}{\partial r} dr + \frac{\partial x}{\partial \theta} d\theta = \cos \theta dr - r \sin \theta d\theta \\ dy = \frac{\partial y}{\partial r} dr + \frac{\partial y}{\partial \theta} d\theta = \sin \theta dr + r \cos \theta d\theta \end{cases}$$

Tangent bundle

informally: union of all tangent spaces of a manifold.

$$TM := \{ (p, V_p) : p \in M, V_p \in T_p M \}$$

tangent bundle



Not $M \times TM$

Cotangent bundle:

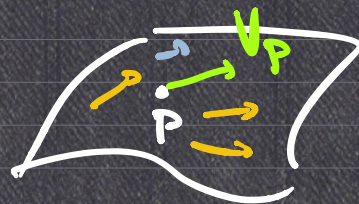
$$T^*M := \{ (p, \alpha_p) : p \in M, \alpha_p \in T_p^* M \}$$

$$X * Y$$

$$= \{ (x, y) : x \in X, y \in Y \}$$

Vector field: $V: M \rightarrow TM$

$$\underbrace{V(p)}_{(p, "V_p")} \in T_p M$$



Claim: TM is a C^∞ -manifold of dimension $= 2 \underbrace{\dim M}_{=n}$.

Proof: $F(u_1, \dots, u_n): \underbrace{U}_{\subset \mathbb{R}^n} \rightarrow \mathcal{O} \subset M$.

$$\begin{aligned} \tilde{F}(u_1, \dots, u_n, x^1, \dots, x^n) &: \underbrace{U \times \mathbb{R}^n}_{\subset \mathbb{R}^{2n}} \rightarrow TM, \\ &:= \left(\underbrace{F(u_1, \dots, u_n)}_{\in M}, \underbrace{\sum_{i=1}^n x^i \frac{\partial}{\partial u_i} \Big|_{F(u_1, \dots, u_n)}}_{\in T_{F(u_1, \dots, u_n)} M} \right) \end{aligned}$$



$$G(v_1, \dots, v_n): \hat{U} \rightarrow \hat{\mathcal{O}} \subset TM.$$

$$\leadsto \tilde{G}(v_1, \dots, v_n, \gamma^1, \dots, \gamma^n) := \left(G(v_1, \dots, v_n), \sum_{j=1}^n \gamma^j \frac{\partial}{\partial v_j} \Big|_{\dots} \right)$$

$$\begin{aligned} &\tilde{G}^{-1} \circ \tilde{F}(u_1, \dots, u_n, x^1, \dots, x^n) \\ &= \tilde{G}^{-1} \left(F(u_1, \dots, u_n), \sum_{i=1}^n x^i \frac{\partial}{\partial u_i} \Big|_{F(u_1, \dots, u_n)} \right) \\ &= \tilde{G}^{-1} \left(F(u_1, \dots, u_n), \sum_{i=1}^n \sum_{j=1}^n x^i \frac{\partial v_j}{\partial u_i} \frac{\partial}{\partial v_j} \right) \\ &= \left(\tilde{G} \circ F(u_1, \dots, u_n), \underbrace{\sum_{i=1}^n x^i \frac{\partial v_1}{\partial u_i}}_{\subset \mathbb{R}^n}, \underbrace{\sum_{i=1}^n x^i \frac{\partial v_2}{\partial u_i}}_{\subset \mathbb{R}^n}, \dots, \underbrace{\sum_{i=1}^n x^i \frac{\partial v_n}{\partial u_i}}_{\subset \mathbb{R}^n} \right) \end{aligned}$$