

MATH 4033 • Spring 2021 • Calculus on Manifolds
Problem Set #2 • Abstract Manifolds • Due Date: 21/03/2019, 11:59PM

Instruction for LaTeX-typers: OK to draw pictures by hand, and use the includegraphics command to incorporate the diagram into your homework.

1. (20 points) Consider the following equivalence relation $\sim$ defined on $\mathbb{R}^2$:

$$(x, y) \sim (x', y') \iff (x', y') = ((-1)^n x + m, (-1)^m y + n) \text{ for some integers } m \text{ and } n.$$

- (a) Sketch an edge-identified square to represent the quotient space $\mathbb{R}^2/\sim$.
 (b) By drawing pictures, explain why $\mathbb{R}^2/\sim$ is homeomorphic to $\mathbb{RP}^2$. No need to write down the explicit homeomorphism.
 (c) Consider the two parametrizations of $\mathbb{R}^2/\sim$:

$$\begin{array}{ll} G_1 : (0, 1) \times (0, 1) \rightarrow \mathbb{R}^2/\sim & G_2 : (0, 1) \times (0.5, 1.5) \rightarrow \mathbb{R}^2/\sim \\ (x, y) \mapsto [(x, y)] & (x, y) \mapsto [(x, y)] \end{array}$$

Find the transition map $G_2^{-1} \circ G_1$.

2. (20 points) Consider two C^∞ scalar functions $f, g : \mathbb{R}^{n \geq 3} \rightarrow \mathbb{R}$, and their non-empty level sets $\Sigma_f := f^{-1}(0)$ and $\Sigma_g := g^{-1}(0)$. Suppose $p \in \Sigma_f \cap \Sigma_g$ is a point such that $\{\nabla f(p), \nabla g(p)\}$ are linearly independent vectors in $\mathbb{R}^n$.

- (a) Show that $\Sigma_f \cap \Sigma_g$ is locally a C^∞ manifold near p , i.e. there exists an open set U in $\mathbb{R}^n$ containing p such that $\Sigma_f \cap \Sigma_g \cap U$ is a C^∞ manifold. What is its dimension?
 (b) Show also that the set $\Sigma_f \cap \Sigma_g \cap U$ in (a) is a submanifold of Σ_f .

3. (20 points) The famous quintic Calabi-Yau 3-fold in string theory is the following subset in $\mathbb{CP}^4$:

$$M := \{[z_0 : z_1 : z_2 : z_3 : z_4] \in \mathbb{CP}^4 : z_0^5 + z_1^5 + z_2^5 + z_3^5 + z_4^5 = 0\}.$$

Show that M is a 6-dimensional submanifold of $\mathbb{CP}^4$ (which is 8 dimensional).

[Hint: First be careful that $\Phi([z_0 : z_1 : z_2 : z_3 : z_4]) = z_0^5 + z_1^5 + z_2^5 + z_3^5 + z_4^5 : \mathbb{CP}^4 \rightarrow \mathbb{C}$ is NOT well-defined! Try to show $M \cap F_i(\mathcal{U})$ is a submanifold of $\mathbb{CP}^4$ for each i where F_i 's are the standard local coordinate charts of $\mathbb{CP}^4$.]

4. (30 points) A Lie group G is a smooth manifold such that multiplication and inverse maps

$$\begin{array}{ll} \mu : G \times G \rightarrow G & \nu : G \rightarrow G \\ (g, h) \mapsto gh & g \mapsto g^{-1} \end{array}$$

are both smooth (C^∞) maps. As an example, $GL(n, \mathbb{R})$ is a Lie group since it is an open subset of $M_{n \times n}(\mathbb{R}) \cong \mathbb{R}^{n^2}$, hence it can be globally parametrized using coordinates of $\mathbb{R}^{n^2}$. The multiplication map is given by products and sums of coordinates in $\mathbb{R}^{n^2}$, hence it is smooth. The inverse map is smooth too by the Cramer's rule $A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$ and that $\det(A) \neq 0$ for any $A \in GL(n, \mathbb{R})$.

- (a) Recall that $T_{(e,e)}(G \times G)$ can be identified with $T_e G \oplus T_e G = \{(X, Y) : X, Y \in T_e G\}$.
 i. Show that the tangent map of μ at (e, e) is given by:

$$(\mu_*)_{(e,e)}(X, Y) = X + Y.$$

- ii. Show that μ is a submersion at (e, e) .

(b) Show that the tangent map of ν at e is given by:

$$(\nu_*)_e(X) = -X.$$

[Hint for part (a): when taking partial derivative $\frac{\partial f}{\partial u}$ at $(u, v) = (u_0, v_0)$, it is OK to substitute $v = v_0$ first, and then differentiate $f(u, v_0)$ by u . It is possible to prove (b) using the result from (a)i and the manifold chain rule in an appropriate way.]