

4.3 Fundamental Theorem of Calculus

4.3.1 Newton-Leibniz's formula

In previous sections we have established the rigorous definition of Riemann integrals. In particular, we proved that any continuous function on $[a, b]$ must be Riemann integrable. However, it is rather impractical to compute $\int_a^b f(x) dx$ via taking a sequence of partitions $\{P_n\}$, as we have seen that even the computation of $\int_0^1 x^p dx$ where $p \in \mathbb{N}$ could involve some summation formulae.

The Fundamental Theorem of Calculus links the Riemann integral of a continuous function with its anti-derivatives, and provides us a very effective way of computing the value of the integral.

Theorem 4.11 — Fundamental Theorem of Calculus. Let f be continuous on $[a, b]$, then we have

$$\frac{d}{dx} \int_a^x f(t) dt = f(x) \quad \text{for any } x \in [a, b]. \quad (4.2)$$

Furthermore, if F is a differentiable function such that $F'(x) = f(x)$ for any $x \in [a, b]$, then

$$\int_a^b f(x) dx = F(b) - F(a). \quad (4.3)$$

(4.3) is known as the **Newton-Leibniz's Formula**. The function F is called an **anti-derivative**, or a **primitive function**, of f .

i Note that $\int_a^x f(t) dt$ is a function of x , not of t . We use t inside the integral $\int_a^x f(t) dt$ because x has appeared as the upper bound of the integral \int_a^x . You can use any other variable too (except x). We usually call t as the *dummy variable*.

Proof. To prove (4.2), we consider the definition of derivatives

$$\begin{aligned} \frac{d}{dx} \int_a^x f(t) dt &= \lim_{h \rightarrow 0} \frac{\int_a^{x+h} f(t) dt - \int_a^x f(t) dt}{h} \\ &= \lim_{h \rightarrow 0} \frac{1}{h} \int_x^{x+h} f(t) dt. \end{aligned}$$

The last step follows from (1) of Proposition 4.10.

By the result of Example 4.7, there exists c between x and $x + h$ such that

$$\frac{1}{h} \int_x^{x+h} f(t) dt = \frac{1}{(x+h) - x} \int_x^{x+h} f(t) dt = f(c).$$

Note that this c depends on both x and h .

Letting $h \rightarrow 0$ (keeping x fixed), by $c \in [x, x+h]$ or $[x+h, x]$, we have $c \rightarrow x$ and so by continuity of f we get

$$\lim_{h \rightarrow 0} f(c) = f(x).$$

This proves (4.2).

For (4.3), we consider

$$\frac{d}{dx} \left(\int_a^x f(t) dt - F(x) \right) = f(x) - f(x) = 0 \quad \text{for any } x \in [a, b]$$

according to (4.2) and the given condition about F .

The only functions with derivatives are constant function (a consequence of the mean value theorem). Therefore, there exists $C \in \mathbb{R}$ such that

$$\int_a^x f(t) dt - F(x) = C \quad \text{for any } x \in [a, b].$$


In particular, putting $x = a$ we get:

$$\underbrace{\int_a^a f(t) dt}_{=0} - F(a) = C \implies C = -F(a).$$

Therefore, we have

$$\int_a^x f(t) dt = F(x) + C = F(x) - F(a) \quad \text{for any } x \in [a, b],$$

and in particular by putting $x = b$, we get (4.3). ■

 We often denote $F(b) - F(a)$ by $[F(x)]_a^b$, $F(x)|_a^b$.

Using (4.3), we can compute the integrals appeared in the previous section very easily – simply find an anti-derivative.

$$\begin{aligned} \frac{d}{dx} \frac{x^{p+1}}{p+1} = x^p \quad \text{where } p \geq 0 &\implies \int_0^1 x^p dx = \left[\frac{x^{p+1}}{p+1} \right]_0^1 = \frac{1^{p+1}}{p+1} - \frac{0^{p+1}}{p+1} = \frac{1}{p+1} \\ \frac{d}{dx} (-\cos x) = \sin x &\implies \int_0^\pi \sin x dx = [-\cos x]_0^\pi = (-\cos \pi) - (-\cos 0) = 2 \\ \frac{d}{dx} e^x = e^x &\implies \int_a^b e^x dx = [e^x]_a^b = e^b - e^a \end{aligned}$$

Continuity is crucial when applying the Newton-Leibniz's formula. The following absurd result would come up if one applies (4.3) blindly on a discontinuous function:

$$\int_{-1}^1 \frac{1}{x^2} dx = \left[-\frac{1}{x} \right]_{-1}^1 = -2 \quad \text{(WRONG!)}$$

Clearly $\frac{1}{x^2} > 0$, so it is absurd for its Riemann integral being negative! The pitfall is that $\frac{1}{x^2}$ is not continuous at 0 which lies in the interval $[-1, 1]$. We cannot apply (4.3) directly!

However, it is perfectly fine to use (4.3) on

$$\int_1^2 \frac{1}{x^2} dx = \left[-\frac{1}{x} \right]_1^2 = -\frac{1}{2} - (-1) = \frac{1}{2},$$

as $\frac{1}{x^2}$ is continuous on $[1, 2]$. We will discuss $\int_0^1 \frac{1}{x^2} dx$ later as the function is unbounded on $[0, 1]$. It is an improper integral.

■ **Exercise 4.23** Find the value of each integral below using Newton-Leibniz's formula:

1. $\int_0^1 \frac{e^x}{1+e^x} dx$
2. $\int_0^\pi x \cos(x^2) dx$
3. $\int_a^b \sin(Ax+B) dx$ where $A \neq 0$ and B are constants.

4.3.2 More uses of the Fundamental Theorem of Calculus

Let's discuss more about the use of (4.2). First note that we stated (4.2) as

$$\frac{d}{dx} \int_a^x f(t) dt = f(x),$$

the lower bound a of the integral can be replaced by any other constant c as

$$\int_c^x f(t) dt = \int_a^x f(t) dt - \int_a^c f(t) dt$$

and $\int_a^c f(t) dt$ is a constant.

However, one should note that the upper bound of the integral must be \int^x otherwise one should consider using the chain rule. Another issue is that (4.2) requires the integrand $f(t)$ to be independent of the differentiate variable x . Let's see some examples:

■ **Example 4.8** Find the derivative with respect to x of each function below. Assume that f is continuous on \mathbb{R} .

$$1. F(x) = \int_0^{x^2} f(t) dt$$

$$2. G(x) = \int_a^x x f(t) dt$$

$$3. H(x) = \int_x^{x^2} f(t) dt$$

■ **Solution** The upper bound of the integral for $F(x)$ is x^2 , we should use the chain rule:

$$\begin{aligned} F'(x) &= \frac{d}{dx} \int_0^{x^2} f(t) dt \\ &= \frac{d}{d(x^2)} \int_0^{x^2} f(t) dt \cdot \frac{d}{dx} x^2 \\ &= f(x^2) \cdot 2x = 2xf(x^2). \end{aligned}$$

For $G(x)$, the integrand $xf(t)$ depends on x , so one must take it out from the integral first before applying (4.2):

$$\int_a^x x f(t) dt = x \int_a^x f(t) dt.$$

The above holds because x is independent of the integration variable t . Then,

$$\begin{aligned} G'(x) &= \frac{d}{dx} \left(x \int_a^x f(t) dt \right) \\ &= \frac{dx}{dx} \int_a^x f(t) dt + x \frac{d}{dx} \int_a^x f(t) dt \\ &= \int_a^x f(t) dt + xf(x). \end{aligned}$$

We cannot proceed further because f is not explicitly given.

For $H(x)$, note that the lower bound is also a function of x , so we first rewrite the integral as:

$$H(x) = \int_x^{x^2} f(t) dt = \underbrace{\int_0^{x^2} f(t) dt}_{G(x)} - \int_0^x f(t) dt.$$

You can replace 0 by any other number provided that f is continuous on the interval of integration. Then we have:

$$H'(x) = G'(x) - f(x) = 2xf(x^2) - f(x).$$

■ **Exercise 4.24** Derive a formula for:

$$\frac{d}{dx} \int_{\beta(x)}^{\alpha(x)} f(t) dt$$

where f is continuous on \mathbb{R} , and α, β are differentiable on \mathbb{R} .

■ **Exercise 4.25** Let $f : \mathbb{R} \rightarrow (0, \infty)$ be continuous function, and consider

$$g(x) := \frac{\left(\int_0^x t f(t) dt \right)^2}{\int_0^x f(t) dt}.$$

Prove that g is strictly increasing on $(0, \infty)$.

■ **Exercise 4.26 — Source: HKAL 1994.** Let $f(x) = \int_1^x \sin(\cos t) dt$.

(a) Show that f is injective on $[0, \pi/2)$.

(b) Find $\left. \frac{d}{dx} f^{-1}(x) \right|_{x=0}$

■ **Exercise 4.27 — Source: HKAL 1997.** Evaluate

$$\lim_{x \rightarrow 0^+} \left(\frac{1}{x^3} \int_0^x e^{t^2} dt - \frac{1}{x^2} \right).$$

■ **Exercise 4.28** Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function. Show that f satisfies the differential equation

$$f'(x) = \sin(1 + f(x)^2) \text{ and } f(0) = a$$

if and only if f satisfies the integral equation

$$f(x) = a + \int_0^x \sin(1 + f(t)^2) dt.$$

Let's discuss more use of (4.2):

Proposition 4.12 Let $f : [a, b] \rightarrow \mathbb{R}$ be a non-negative continuous function. Suppose

$$\int_a^b f(x) dx = 0,$$

then $f(x) \equiv 0$ on $[a, b]$.

Proof. It is quite an expected result since $\int_a^b f(x) dx$ is the area under the graph $y = f(x)$ for a non-negative function f . If the area is zero, the only possibility is the function is 0. As we also assume f is continuous, we rule out those function which is 0 except a finite number of point too.

To prove it rigorously, we consider the function

$$F(t) := \int_a^t f(x) dx.$$

By (4.2), we have $F'(t) = f(t) \geq 0$. Hence F is increasing on $[a, b]$. However, we also note that

$$F(a) = \int_a^a f(x) dx = 0 \quad \text{and} \quad F(b) = \int_a^b f(x) dx = 0 \quad (\text{given}).$$

Therefore, $F(t)$ is identically zero on $[a, b]$ since:

$$0 = F(a) \leq F(t) \leq F(b) = 0 \quad \forall t \in [a, b].$$

This prove $f(t) = F'(t) = 0$ on $[a, b]$. ■

■ **Exercise 4.29 — Source: HKAL 1998.** Answer the following questions:

- (a) [This part just asked for the proof of Proposition 4.12, hence omitted here.]
 (b) Let g be a continuous function on $[a, b]$. Suppose

$$\int_a^b g(x)u(x) dx = 0$$

for any continuous function u on $[a, b]$, show that $g(x) = 0$ for all $x \in [a, b]$.

- (c) Let h be a continuous function on $[a, b]$. Define

$$A = \frac{1}{b-a} \int_a^b h(t) dt.$$

- (i) If $v(x) = h(x) - A$ for all $x \in [a, b]$, show that $\int_a^b v(x) dx = 0$.

- (ii) If $\int_a^b h(x)w(x) dx = 0$ for any continuous function w on $[a, b]$ satisfying $\int_a^b w(x) dx = 0$, show that $h(x) = A$ for all $x \in [a, b]$.

4.3.3 Indefinite integrals

In view of the Newton-Leibniz's formula (4.3), we can evaluate a Riemann integral $\int_a^b f(x) dx$ by finding an anti-derivative of f . This relates the problem of finding area with (the reverse process of) differentiations. Because of this connection, we introduce the notion of **indefinite integrals** which *symbolically* looks like a Riemann integral but *conceptually* different:

Definition 4.6 — Indefinite Integrals. Suppose f is a function defined on an interval I , then the **indefinite integral** of f is defined to be:

$$\int f(x) dx := \{F(x) : F'(x) = f(x) \text{ on } I\}.$$

If F_0 is a particular anti-derivative of f , then any other anti-derivative F of f on I would differ from F_0 by a constant, then we also have

$$\int f(x) dx := \{F_0(x) + C : C \text{ is a real constant}\}.$$

Usually, we abbreviate the above by $\int f(x) dx = F_0(x) + C$ so that students who are not taking honor calculus could understand the notation.

i Naturally, $\int_a^b f(x) dx$ will then be called a **definite integral** of f . It is computationally similar to the indefinite integral $\int f(x) dx$ in view of the Newton-Leibniz formula, but as a math major, you should be very clear about their conceptual difference. You should regards $\int f(x) dx$ as

$$\left(\frac{d}{dx}\right)^{-1} f$$

where $\frac{d}{dx}$ is regarded as an operator.

Here are some examples:

$$\begin{aligned}\frac{d}{dx} \sin x &= \cos x \implies \int \cos x dx = \sin x + C \\ \frac{d}{dx} \left(\frac{x^p}{p+1} \right) &= x^p \quad \text{where } p \neq -1 \implies \int x^p dx = \frac{x^{p+1}}{p+1} + C \\ \frac{d}{dx} \frac{1}{\sqrt{1-x^2}} &= \sin^{-1} x \implies \int \frac{1}{\sqrt{1-x^2}} dx = \sin^{-1} x + C\end{aligned}$$

When writing an indefinite integral, we often implicitly assume that the domain of both f and F is an interval I which is connected. Consider a function f defined on a disjoint union of two intervals:

$$f(x) = \begin{cases} x^3 & \text{if } x \in (0, 1) \\ x^4 & \text{if } x \in (2, 3) \end{cases}.$$

One anti-derivative of f is certainly

$$F_0(x) = \begin{cases} \frac{x^4}{4} & \text{if } x \in (0, 1) \\ \frac{x^5}{5} & \text{if } x \in (2, 3) \end{cases},$$

but the others may be of the form

$$F(x) = \begin{cases} \frac{x^4}{4} + C_1 & \text{if } x \in (0, 1) \\ \frac{x^5}{5} + C_2 & \text{if } x \in (2, 3) \end{cases},$$

where C_1 and C_2 are two real constants, so it is not necessarily of the form $F_0(x) + C$. Therefore it would be **problematic** to say

$$\int f(x) dx = F_0(x) + C.$$

When writing

$$\int \frac{1}{x^2} dx = -\frac{1}{x} + C,$$

we should implicitly assume the domain involved is an interval not containing 0, such as $(-2, -1)$ or $[1, 3)$, but not $(-1, 1]$.

The indefinite integral $\int \frac{1}{x} dx$ worths some discussion. On the interval $(0, \infty)$, an anti-derivative of $\frac{1}{x}$ is clearly $\log x$, but $\log x$ is undefined if on the interval $(-\infty, 0)$. Instead, the anti-derivative of $\frac{1}{x}$ on the interval $(-\infty, 0)$ is $\log(-x)$ because by chain rule:

$$\frac{d}{dx} \log(-x) = \frac{d}{d(-x)} \log(-x) \cdot \frac{d(-x)}{dx} = \frac{1}{(-x)} \cdot (-1) = \frac{1}{x}.$$

Therefore, we have $\int \frac{1}{x} dx = \log x + C$ when the domain interval in the context is a subset of $(0, \infty)$, while $\int \frac{1}{x} dx = \log(-x) + C$ when the domain is a subset of $(-\infty, 0)$. However, we often write it in a unified way:

$$\int \frac{1}{x} dx = \log |x| + C,$$

so that it applies to both interval types. Again, if the domain in the context is an interval like $(-1, 1)$, it does not make sense to talk about $\int \frac{1}{x} dx$ as the integrand $\frac{1}{x}$ is undefined at 0.

Many of might have known that

$$\int \tan x \, dx = -\log |\cos x| + C = \log |\sec x| + C.$$

Similarly, when writing this we implicitly assume the interval I involved is one that either $\cos x > 0$ on I , or $\cos x < 0$ on I .

We should also be careful when the function f is piecewise defined, such as

$$f(x) = \begin{cases} e^x & \text{if } x \geq 0 \\ 1 & \text{if } x < 0 \end{cases}.$$

It is NOT true that

$$\int f(x) \, dx = \begin{cases} e^x + C & \text{if } x \geq 0 \\ x + C & \text{if } x < 0 \end{cases}, \quad \text{where } C \text{ is any real constant} \quad (\text{WRONG!})$$

or

$$\int f(x) \, dx = \begin{cases} e^x + C_1 & \text{if } x \geq 0 \\ x + C_2 & \text{if } x < 0 \end{cases}, \quad \text{where } C_1, C_2 \text{ are any real constants} \quad (\text{WRONG!})$$

The function

$$F(x) = \begin{cases} e^x + C & \text{if } x \geq 0 \\ x + C & \text{if } x < 0 \end{cases}$$

is not even continuous at 0 as $\lim_{x \rightarrow 0+} F(x) = C + 1$ whereas $\lim_{x \rightarrow 0-} F(x) = C$. The same for functions

$$\begin{cases} e^x + C_1 & \text{if } x \geq 0 \\ x + C_2 & \text{if } x < 0 \end{cases}$$

unless C_1 and C_2 are some carefully chosen constants.

In fact, one of the anti-derivative of f should be

$$F_0(x) = \begin{cases} e^x & \text{if } x \geq 0 \\ x + 1 & \text{if } x < 0 \end{cases},$$

so we should write

$$\int f(x) \, dx = F_0 + C = \begin{cases} e^x & \text{if } x \geq 0 \\ x + 1 & \text{if } x < 0 \end{cases} + C$$

where C is any real constant.

■ **Exercise 4.30** Compute the indefinite integral of the function:

$$f(x) = \begin{cases} x^2 & \text{if } x \geq 0 \\ \sin x & \text{if } x < 0 \end{cases}.$$

Also, compute $\int |x| \, dx$ (take the domain to be \mathbb{R})

Analogous results of (2) and (3) in Proposition 4.10 for Riemann (i.e. definite) integrals also hold for indefinite integral, such as

$$\int_c f(x) \, dx = c \int f(x) \, dx \quad \text{and} \quad \int (f(x) + g(x)) \, dx = \int f(x) \, dx + \int g(x) \, dx.$$

The proof is much easier. To prove the second statement, we take anti-derivatives F of f , and G of g . Then, we have

$$\int f(x) dx + \int g(x) dx = F(x) + C_1 + G(x) + C_2$$

where C_1, C_2 are any real constants. Since $(F + G)' = f + g$ by the linearity of differentiations, $F + G$ is an anti-derivative of $f + g$ and so

$$\int (f(x) + g(x)) dx = F(x) + G(x) + C_3$$

where C_3 is any real constant. We are only left to show

$$\{C_1 + C_2 : C_1, C_2 \in \mathbb{R}\} = \{C_3 : C_3 \in \mathbb{R}\}$$

which is trivial (just prove both \subset and \supset).