

Lecture 22

07/05/2020

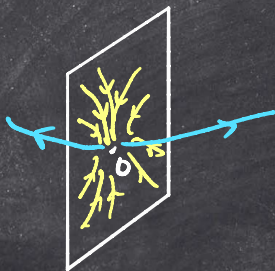
$$r > 1$$

$$\sigma > b+1$$

$$D\mathcal{L}(0,0,0) = \begin{bmatrix} -\sigma & \sigma & 0 \\ r & -1 & 0 \\ 0 & 0 & -b \end{bmatrix}$$

eigenvalues $\lambda = \underbrace{-b}_{\ominus}, \frac{1}{2} \left(\underbrace{-(\sigma+1)}_{\ominus} \pm \underbrace{\sqrt{(\sigma+1)^2 - 4\sigma(1-r)}}_{+} \right)$

(Note: A blue arrow points from a blue $\oplus$ to the plus sign in the square root, and a yellow arrow points from a yellow $\ominus$ to the minus sign in the square root.)



$$Q_{\pm} = (\pm \sqrt{b(r-1)}, \pm \sqrt{b(r-1)}, r-1)$$

$$\boxed{r > 1}$$

Direct computation $\Rightarrow \det(D\mathcal{L}(Q_{\pm}) - \lambda I) = 0$

$$\Leftrightarrow \underbrace{\lambda^3 + (1+b+\sigma)\lambda^2 + b(\sigma+r)\lambda + 2b\sigma(r-1)}_{p(\lambda)} = 0.$$

$\lambda \geq 0$ $\Rightarrow p(\lambda) \geq 2b\sigma(r-1) > 0$.

$\Rightarrow$ all real roots of $p(\lambda)$ must be negative.

$r=1$: eigenvalues

$$\lambda^3 + (1+b+\sigma)\lambda^2 + b(\sigma+1)\lambda = 0.$$

$$\Rightarrow \lambda = 0, -b, -\sigma-1.$$

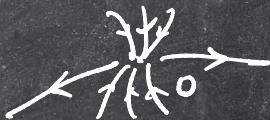
$$\sigma > b+1$$

near

$r \approx 1$: eigenvalues are all distinct (real).

Conclusion:

$\exists \delta > 0$ s.t. $1 < r < \underbrace{(\delta + 1)}_{= \sigma(\frac{\sigma + \gamma + 1}{\sigma - \gamma - 1})} \Rightarrow Q_{\pm}$ is asymptotically stable.



From now, take $r \gg 1$.

A is invariant ~~def~~ $\left(y \in A \Rightarrow \varphi_t(y) \in A \quad \forall t \in (-\infty, \infty) \right)$.

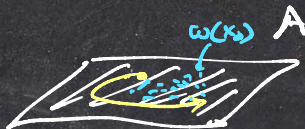
$\omega(x_0)$ is an invariant set

Proof: $y \in \omega(x_0) \Rightarrow y = \lim_{n \rightarrow \infty} \varphi_{t_n}(x_0)$

$$\Rightarrow \varphi_s(y) = \lim_{n \rightarrow \infty} \varphi_{s+t_n}(x_0) \in \omega(x_0).$$

$$\forall s \in \mathbb{R}.$$

Goal: Search for invariant set A ^{closed} for the Lorenz system.

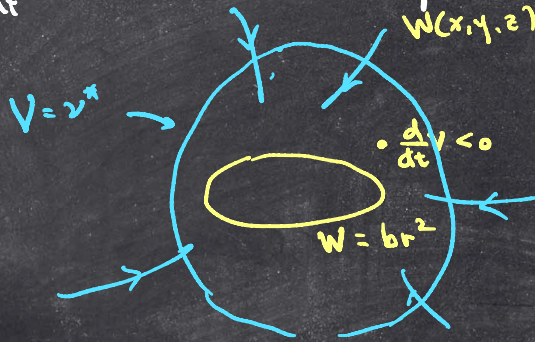


$$x_0 \in A \Rightarrow \omega(x_0) \subset A.$$

Claim: $\exists$ ellipsoid $\underbrace{rx^2 + \sigma y^2 + \sigma(z-2r)^2}_{V(x,y,z)} = \underbrace{v^*}_{\text{const.}}$

s.t. any solution to the Lorenz system must eventually enter the $\{V = v^*\}$ and stay there for all future time.

Proof: $\frac{d}{dt} V(\vec{x}(t)) = -2\sigma \left(\underbrace{rx^2 + y^2 + b(z-r)^2}_{W(x,y,z)} - br^2 \right)$



Cor: $\forall x_0 \in \mathbb{R}^3$
 $w(x_0) \subset \{V \leq v^*\}$

Claim:



$D_t := \varphi_t(D_0)$ Then $\text{vol}(D_t) \rightarrow 0$
as $t \rightarrow \infty$.

Cor:

$A \rightarrow$  D_0
invariant.

$\varphi_t(D_0) \supset A$

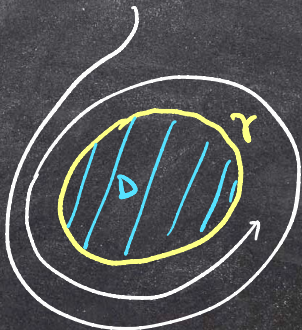


$\text{vol}(A) = 0$.

$\text{vol}(\varphi_t(D_0)) \geq \text{vol}(A)$

$\downarrow$
0 as $t \rightarrow \infty$.

In contrast:
in $\mathbb{R}^2$.



$\gamma \cup D$ invariant.

Proof of claim

$$\frac{d}{dt} \text{vol}(D_t) = \int_{\partial D_t} \langle \vec{L}, \hat{n} \rangle dS$$

$$= \int_{D_t} \text{div} \vec{L} dV$$

$$= \int_{D_t} \underbrace{-(\sigma + 1 + b)}_{\textcircled{+}} dV = -(\sigma + 1 + b) \text{vol}(D_t).$$

$$\Rightarrow \text{vol}(D_t) = \text{vol}(D_0) \cdot e^{-(\sigma + 1 + b)t} \rightarrow 0 \text{ as } t \rightarrow \infty.$$

