

• Chapter 02 : Existence and Uniqueness.

$$\begin{cases} \vec{x}' = \vec{F}(\vec{x}, t) \\ \vec{x}(0) = \vec{x}_0 \end{cases}$$

OR

$$\begin{cases} \vec{x}' = \vec{G}(\vec{x}) \\ \vec{x}(0) = \vec{x}_0 \end{cases}$$

Non-Autonomous

Autonomous.

- Prop. 2.3 : Let \vec{F} be continuous, $\vec{x}_0 \in \mathbb{R}^d$

$$\vec{x}(t) \text{ solves } \begin{cases} \vec{x}' = \vec{F}(\vec{x}, t) \\ \vec{x}(0) = \vec{x}_0 \end{cases} \Leftrightarrow \vec{x}(t) \text{ is a continuous solution to } \vec{x}(t) = \vec{x}_0 + \int_0^t \vec{F}(\vec{x}(s), s) ds$$

Idea :

$$\vec{x}_n(t) = \vec{x}_0 + \int_0^t \vec{F}(\vec{x}_n(s), s) ds$$

$$\lim_{n \rightarrow \infty} \vec{x}_n(t) = \vec{x}_0 + \underbrace{\lim_{n \rightarrow \infty} \int_0^t \vec{F}(\vec{x}_n(s), s) ds}_{\text{---}}$$

- Picard-Lindelöf Existence Theorem.

- Picard iteration sequence. $\{\vec{x}_n(t)\}_{n=0}^{\infty}$

$$\vec{x}_0(t) = \vec{x}_0 \quad (\text{Abuse of notation})$$

$$\vec{x}_n(t) := \vec{x}_0 + \int_0^t \vec{F}(\vec{x}_{n-1}(s), s) ds$$

- Example : Consider $\begin{cases} x' = -x \\ x(0) = 0, x'(0) = 1 \end{cases}$

Let $v = x'$, then

$$\vec{x} = \begin{bmatrix} x \\ v \end{bmatrix}, \vec{x}' = \begin{bmatrix} x \\ v \end{bmatrix}' = \begin{bmatrix} v \\ -x \end{bmatrix}, \vec{x}(0) = \begin{bmatrix} x(0) \\ v(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

By prop. 2.3. The IVP is equivalent to

$$\vec{x}(t) = \vec{x}_0 + \int_0^t \vec{F}(\vec{x}(s)) ds.$$

$$\begin{bmatrix} x \\ v \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \int_0^t \begin{bmatrix} v(s) \\ -x(s) \end{bmatrix} ds, \vec{x}_0(t) = \vec{x}_0$$

$$\vec{x}_1(t) = \begin{bmatrix} 0 + \int_0^t v(s) ds \\ 1 - \int_0^t x(s) ds \end{bmatrix} = \begin{bmatrix} \int_0^t 1 ds \\ 1 - \int_0^t 0 ds \end{bmatrix} = \begin{bmatrix} t \\ 1 \end{bmatrix}$$

$$\begin{cases} \vec{x}'(t) = \vec{F}(\vec{x}, t) \\ \vec{x}(0) = \vec{x}_0 \end{cases}$$

$$\vec{x}_2(t) = \begin{bmatrix} t \\ 1 - \frac{t^2}{2} \end{bmatrix}, \quad \vec{x}_3(t) = \begin{bmatrix} t - \frac{t^3}{3!} \\ 1 - \frac{t^2}{2} \end{bmatrix}.$$

$$\vec{x}_4(t) = \begin{bmatrix} t - \frac{t^3}{3!} \\ 1 - \frac{t^2}{2} + \frac{t^4}{4!} \end{bmatrix}$$

"Guess" :

$$\vec{x}_{2n}(t) = \begin{bmatrix} \sum_{k=1}^n \frac{(-1)^{k-1} t^{2k-1}}{(2k-1)!} \\ \sum_{k=0}^n \frac{(-1)^k t^{2k}}{(2k)!} \end{bmatrix}$$

$n \in \mathbb{N}$.

$$\vec{x}_{2n+1}(t) = \begin{bmatrix} \sum_{k=1}^n \frac{(-1)^{k-1} t^{2k-1}}{(2k-1)!} \\ \sum_{k=0}^{n+1} \frac{(-1)^k t^{2k}}{(2k)!} \end{bmatrix}$$

Can prove by induction.

$$\text{As } n \rightarrow \infty, \quad \sum_{k=1}^n \frac{(-1)^{k-1} t^{2k-1}}{(2k-1)!} \rightarrow \sin t$$

$$\sum_{k=0}^n \frac{(-1)^k t^{2k}}{(2k)!} \rightarrow \cos t.$$

$$\Rightarrow \vec{x}_\infty(t) = \begin{bmatrix} x_\infty(t) \\ y_\infty(t) \end{bmatrix} = \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

$$\begin{cases} 'x' = -x \\ \underline{x(0) = 0}, \quad \underline{x'(0) = 1} \\ \downarrow \\ A = 0 \end{cases}$$

Plug e^{rt} into it. $\Rightarrow r = \pm i$

General Sol: $x(t) = A \cos t + B \sin t$.

$$\Rightarrow x(t) = \sin t.$$

- Lipschitz Continuity / Locally Lipschitz continuous.

$$\vec{F}: \Omega \times I \rightarrow \mathbb{R}^m, \quad \Omega \subset \mathbb{R}^d$$

$$\vec{F} \text{ is Lipschitz cont.} \stackrel{\text{def}}{\iff} \exists L > 0, \text{ s.t.} \quad \vec{F}(\vec{x}, t) - \vec{F}(\vec{y}, t) \leq L |\vec{x} - \vec{y}| \quad \forall \vec{x}, \vec{y} \in \Omega$$

\vec{F} is cont. on $\Omega \times I$
pick $\delta = \frac{\epsilon}{L}$

- Lipschitz cont. func.: $\sin(x)$, $\cos(x)$ (on \mathbb{R})

- Lipschitz cont. on \mathbb{R} , but not differentiable everywhere: $|x|$

- Lipschitz cont. on \mathbb{R} , differentiable on \mathbb{R} . $f(x) = \begin{cases} x^2 \sin(\frac{1}{x}) & x \neq 0 \\ 0 & x = 0 \end{cases}$

- Not Lipschitz cont. on \mathbb{R} , but are C^∞ : x^2, e^x

(But locally Lipschitz cont. on \mathbb{R})

- Locally Lipschitz continuous, on $\Omega \times I$. ← Open.

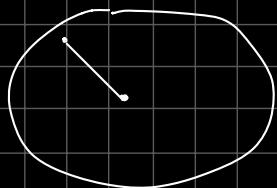
$$\vec{F} : \Omega \times I \rightarrow \mathbb{R}^m.$$

if $\forall \vec{x}_0 \in \Omega$, \exists open ball $B_r(\vec{x}_0) \subset \Omega$, s.t.



\vec{F} is Lipschitz cont. on $B_r(\vec{x}_0) \times I$.

- If \vec{F} is differentiable on Ω and I ← convex.
we have $|x|$ is not diff. at $x=0$.



\vec{F} is Lipschitz cont. on $\Omega \times I$

$$\Leftrightarrow \left| \frac{\partial F_i}{\partial x_j} \right| \leq C \quad \text{for all } i, j, \quad \text{for all } (\vec{x}, t) \in \Omega \times I.$$

$$\Leftrightarrow \underbrace{\|\vec{DF}\|}_{\text{Jacobian.}} \leq \tilde{C} \quad \forall (\vec{x}, t) \in \Omega \times I$$

- C' \Rightarrow locally Lipschitz cont. (on $\Omega \times I$) open, convex.
closed, bounded.

Examples.

Show $f(x) = \begin{cases} x^2 \sin(\frac{1}{x}) & x \neq 0 \\ 0 & x = 0 \end{cases}$ is Lipschitz cont. on \mathbb{R} .
differentiable on \mathbb{R} .
but not C' .

$$\lim_{x \rightarrow 0} f(x) = \lim_{x \rightarrow 0} x^2 \sin\left(\frac{1}{x}\right) = 0 \Rightarrow f \text{ is cont. on } \mathbb{R}.$$

$$\text{For } x \neq 0, \quad f'(x) = 2x \sin\left(\frac{1}{x}\right) - \cos\left(\frac{1}{x}\right).$$

$$\text{For } x = 0, \quad \lim_{x \rightarrow 0} \frac{f(x) - f(0)}{x - 0} = \lim_{x \rightarrow 0} x \sin\left(\frac{1}{x}\right) = 0$$

$$\text{but } \lim_{x \rightarrow 0} 2x \sin\left(\frac{1}{x}\right) - \cos\left(\frac{1}{x}\right) = \lim_{x \rightarrow 0} -\cos\left(\frac{1}{x}\right) \neq 0$$

$$f'(x) = 2x \sin\left(\frac{1}{x}\right) - \cos\left(\frac{1}{x}\right).$$

$$|f'(x)| = 2 \underbrace{|x \sin\left(\frac{1}{x}\right)|}_{\leq 1} + \underbrace{|\cos\left(\frac{1}{x}\right)|}_{\leq 1} \leq 3. \Rightarrow f \text{ is Lips. cont.}$$

$$\lim_{x \rightarrow \infty} \frac{\sin(x)}{1/x} = 1$$

- Composition of Lipschitz cont. functions.

$$F : \Omega \rightarrow \mathbb{R}, \quad G : F(\Omega) \rightarrow \mathbb{R}$$

$G \circ F : \Omega \rightarrow \mathbb{R}$ is Lipschitz continuous on Ω

For $x, y \in \Omega$,

$$\begin{aligned} & |G(F(x)) - G(F(y))| \quad (\text{Since } F(x), F(y) \in F(\Omega)) \\ & \leq L_G |F(x) - F(y)| \\ & \leq L_F \cdot L_G |x - y| = L |x - y|. \quad \square \end{aligned}$$