

- Today's coverage : Chapter 01 (linear system of ODE)

Review : Matrix Exponential, Matrix Norm,
Existence and uniqueness of solution of linear system $\vec{x}' = A\vec{x}$

- Examples on calculating matrix exponentials for different A .

In 1D : $x' = ax \Rightarrow x(t) = e^{at} x_0$
 $x(0) = x_0$

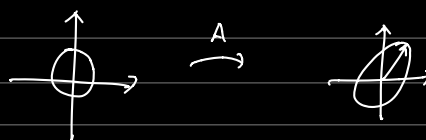
$\Rightarrow$ Generalize : $\vec{x}' = A\vec{x} \stackrel{?}{\Rightarrow} x(t) = e^{At} \vec{x}_0$
 $\vec{x}(0) = \vec{x}_0$

Two Problems : ① $e^{At} := \sum_{k=0}^{\infty} \frac{(At)^k}{k!}$ $\rightarrow A^k$ why it converges?
② show $\frac{d}{dt} e^{At} = A e^{At}$

Need matrix norm for that :

$$\|A\| := \sup \{ |A\vec{x}| : |\vec{x}| = 1 \}$$

$\uparrow$
CAN BE NON-SQUARE



Five properties of it :

- ① $\|A\| \geq 0$ and $\|A\| = 0 \Leftrightarrow A = 0$
- ② $\|cA\| = |c| \cdot \|A\| \quad \forall c \in \mathbb{R}$
- ③ $\|A+B\| \leq \|A\| + \|B\|$
- ④ $|A\vec{x}| \leq \|A\| \cdot |\vec{x}| \quad \forall \vec{x} \in \mathbb{R}^d$
- ⑤ $\|AB\| \leq \|A\| \cdot \|B\|$ (sub-multiplicative)

$$\Rightarrow \|A^n\| \leq \|A\|^n \text{ for square } A.$$

$\Rightarrow$ Show $\vec{x}(t) = e^{At} \vec{x}_0$ is a solution to $\begin{cases} \vec{x}' = A\vec{x} \\ \vec{x}(0) = \vec{x}_0 \end{cases}$

- Examples

① $D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$, then $e^D = \begin{bmatrix} e^{\lambda_1} & \\ & e^{\lambda_2} \end{bmatrix}$

② $J = \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix}$, then $e^J = \begin{bmatrix} e^\lambda & e^\lambda \\ 0 & e^\lambda \end{bmatrix}$

③ Consider e^{Jt}

$$J^2 = \begin{bmatrix} \lambda^2 & 2\lambda \\ 0 & \lambda^2 \end{bmatrix}, J^3 = \begin{bmatrix} \lambda^3 & 3\lambda^2 \\ 0 & \lambda^3 \end{bmatrix}, \dots, J^k = \begin{bmatrix} \lambda^k & k\lambda^{k-1} \\ 0 & \lambda^k \end{bmatrix}$$

$$e^{Jt} = \sum_{k=0}^{\infty} \frac{J^k t^k}{k!} = \sum_{k=0}^{\infty} \frac{t^k}{k} \begin{bmatrix} \lambda^k & k\lambda^{k-1} \\ 0 & \lambda^k \end{bmatrix} = \begin{bmatrix} e^{\lambda t} & t e^{\lambda t} \\ 0 & e^{\lambda t} \end{bmatrix}$$

Consider $\sum_{k=0}^{\infty} \frac{t^k}{k!} \cdot k \lambda^{k-1} = \sum_{k=1}^{\infty} \frac{t^k}{k!} \cdot k \lambda^{k-1} = \sum_{k=1}^{\infty} \frac{t^k \lambda^{k-1}}{(k-1)!}$

$$= t \sum_{k=1}^{\infty} \frac{t^{k-1} \lambda^{k-1}}{(k-1)!} = t e^{\lambda t}$$

$$Q = \begin{bmatrix} \alpha & \beta \\ -\beta & \alpha \end{bmatrix} \quad (\text{Homework})$$

$$(4) \quad A = \begin{bmatrix} 0 & -\theta \\ \theta & 0 \end{bmatrix} \quad (\text{Example 1.5})$$

observe the pattern, $A^2 = \begin{bmatrix} -\theta^2 & 0 \\ 0 & -\theta^2 \end{bmatrix} = -\theta^2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$A^3 = \begin{bmatrix} 0 & \theta^3 \\ -\theta^3 & 0 \end{bmatrix} = -\theta^3 \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\dots, \quad A^{2k} = (-1)^k \theta^{2k} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad A^{2k+1} = (-1)^k \theta^{2k+1} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

for $k \in \mathbb{N} \cup \{0\}$

$$e^A = \sum_{k=0}^{\infty} \frac{A^k}{k!} = \sum_{k=0}^{\infty} \frac{A^{2k}}{(2k)!} + \sum_{k=0}^{\infty} \frac{A^{2k+1}}{(2k+1)!}$$

$$= \underbrace{\sum_{k=0}^{\infty} \frac{(-1)^k \theta^{2k}}{(2k)!} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}_{\cos \theta} + \underbrace{\sum_{k=0}^{\infty} \frac{(-1)^k \theta^{2k+1}}{(2k+1)!} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}}_{\sin \theta}$$

$$= \cos \theta \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \sin \theta \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

(5) Nilpotent matrix: if $A^n = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ for some integer n .
then we say A is Nilpotent.

$$e^A = \sum_{k=0}^{\infty} \frac{A^k}{k!} = I + A + \dots + A^n$$

$$A = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}, \quad A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\Rightarrow e^A = I + A = \begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix}$$

• Exercise 1.20: (1) $e^{PAP^{-1}} = P e^A P^{-1}$

$$e^{PAP^{-1}} = \sum_{k=0}^{\infty} \frac{(PAP^{-1})^k}{k!} = \sum_{k=0}^{\infty} \frac{P A^k P^{-1}}{k!} = P \left[\sum_{k=0}^{\infty} \frac{A^k}{k!} \right] P^{-1} = P e^A P^{-1}$$

(2) $A e^A = e^A \cdot A$

$$A \sum_{k=0}^{\infty} \frac{A^k}{k!} = \sum_{k=0}^{\infty} \frac{A^{k+1}}{k!} = \sum_{k=0}^{\infty} \frac{A^k \cdot A}{k!} = e^A \cdot A$$

Diagonalizable

③ if $AB = BA$, then $e^A \cdot e^B = e^B \cdot e^A = e^{A+B}$.
Use it to express $\exp \begin{bmatrix} \alpha & -\beta \\ \beta & \alpha \end{bmatrix}$.

$A = L + N$
(Nilpotent.)

$$\begin{bmatrix} \alpha & -\beta \\ \beta & \alpha \end{bmatrix} = \begin{bmatrix} \alpha & \\ & \alpha \end{bmatrix} + \begin{bmatrix} & -\beta \\ \beta & \end{bmatrix}$$

• Continuous Dependence. (Thm. 1.29)

$A : d \times d$. $\vec{x}_0, \vec{y}_0 \in \mathbb{R}^d$

$\vec{x}(t), \vec{y}(t)$ solves $\begin{cases} \vec{x}' = A\vec{x} \\ \vec{x}(0) = \vec{x}_0 \end{cases}$, $\begin{cases} \vec{y}' = A\vec{y} \\ \vec{y}(0) = \vec{y}_0 \end{cases}$.

then $|\vec{x}(t) - \vec{y}(t)| \leq |\vec{x}_0 - \vec{y}_0| e^{\|A\| \cdot |t|} \quad \forall t \in \mathbb{R}$.

Recall Proof : $\frac{d}{dt} |\vec{x}(t) - \vec{y}(t)|^2$. . .

Problematic Proof : we know $\begin{bmatrix} \vec{x}(t) = e^{At} \vec{x}_0 \\ \vec{y}(t) = e^{At} \vec{y}_0 \end{bmatrix}$. $(\because \|e^{At}\| \leq e^{\|A\| \cdot |t|})$

$|\vec{x}(t) - \vec{y}(t)| = \underbrace{\|e^{At}\|}_{\text{matrix}} \underbrace{(\vec{x}_0 - \vec{y}_0)}_{\text{vector}} \leq \|e^{At}\| \cdot |\vec{x}_0 - \vec{y}_0| \leq e^{\|A\| \cdot |t|} |\vec{x}_0 - \vec{y}_0|$

We haven't show the solution is unique

① Generalize $\vec{x}(t) = e^{at} x_0$ to $\vec{x}(t) = e^{At} \vec{x}_0$. (Existence)

(use matrix norm) (i) why e^{At} is well-defined.
(ii) why $\frac{d}{dt} e^{At} = A e^{At}$.

② Continuous Dependence : $|\vec{x}(t) - \vec{y}(t)| \leq |\vec{x}_0 - \vec{y}_0| e^{\|A\| \cdot |t|} \quad \forall t \in \mathbb{R}$.

if $|\vec{x}_0 - \vec{y}_0| \rightarrow 0 \Rightarrow$ Uniqueness of sol. $\|A\|$ can be very large

In Chapter 2 : Nonlinear system. $\vec{x}' = \vec{F}(\vec{x}(t), t) / \vec{G}(\vec{x}(t))$