

$\exists \hat{n}: \Sigma \rightarrow S^2(\mathbb{R})$ smooth map s.t. $\hat{n}(p)$ is a unit normal to Σ at p .
 $\hat{n} \Rightarrow$ orientable surface.

$F(u, v_2) = (x(u, v_2), y(u, v_2), z(u, v_2))$

$\hat{n}_F = \frac{\frac{\partial F}{\partial u_1} \times \frac{\partial F}{\partial u_2}}{\left| \frac{\partial F}{\partial u_1} \times \frac{\partial F}{\partial u_2} \right|}$

$\frac{\partial F}{\partial u_1} = \begin{pmatrix} x_u \\ y_u \\ z_u \end{pmatrix}$, $\frac{\partial F}{\partial u_2} = \begin{pmatrix} x_{u_2} \\ y_{u_2} \\ z_{u_2} \end{pmatrix}$

$\hat{n}_G = \frac{\det \begin{pmatrix} \frac{\partial x}{\partial u_1} & \frac{\partial x}{\partial u_2} \\ \frac{\partial y}{\partial u_1} & \frac{\partial y}{\partial u_2} \\ \frac{\partial z}{\partial u_1} & \frac{\partial z}{\partial u_2} \end{pmatrix}}{\left| \det \begin{pmatrix} \frac{\partial x}{\partial u_1} & \frac{\partial x}{\partial u_2} \\ \frac{\partial y}{\partial u_1} & \frac{\partial y}{\partial u_2} \\ \frac{\partial z}{\partial u_1} & \frac{\partial z}{\partial u_2} \end{pmatrix} \right|} \hat{n}_F$

$F: (-1, 1) \times (0, 2\pi) \rightarrow S^2$

$F(u, \theta) = \begin{pmatrix} (3+u \cos \frac{\theta}{2}) \cos \theta \\ (3+u \cos \frac{\theta}{2}) \sin \theta \\ u \sin \frac{\theta}{2} \end{pmatrix}$

$\tilde{F}: (-1, 1) \times (-\pi, \pi) \rightarrow S^2$

$\tilde{F}(u, \theta) = \begin{pmatrix} (3+u \cos \frac{\theta}{2}) \cos \theta \\ (3+u \cos \frac{\theta}{2}) \sin \theta \\ u \sin \frac{\theta}{2} \end{pmatrix}$

$G(u, v_2) = (x, y, z)$

$\hat{n}_G = \frac{\det \begin{pmatrix} \frac{\partial x}{\partial u_1} & \frac{\partial x}{\partial u_2} \\ \frac{\partial y}{\partial u_1} & \frac{\partial y}{\partial u_2} \\ \frac{\partial z}{\partial u_1} & \frac{\partial z}{\partial u_2} \end{pmatrix}}{\left| \det \begin{pmatrix} \frac{\partial x}{\partial u_1} & \frac{\partial x}{\partial u_2} \\ \frac{\partial y}{\partial u_1} & \frac{\partial y}{\partial u_2} \\ \frac{\partial z}{\partial u_1} & \frac{\partial z}{\partial u_2} \end{pmatrix} \right|} \hat{n}_F$

chain rule: $\frac{\partial x}{\partial u_1} = \frac{\partial x}{\partial u_1} \frac{\partial u_1}{\partial u_1} + \dots$

$\hat{n}_G = \hat{n}_F$

$G \circ F(u, v_2) = (u, v_2)$

$F^{-1} \circ G(u, v_2) = (u, v_2)$

Definition: M is an orientable manifold

$\hat{n} \Leftrightarrow \exists$ atlas $\{F_\alpha: U_\alpha \rightarrow \mathbb{R}^n\}$ of M such that $\det D(F_\alpha^{-1} \circ F_\beta) > 0 \quad \forall \alpha, \beta$ (overlapping).

$D(F_\alpha^{-1} \circ F_\beta)$

$= \begin{cases} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} & \text{if } \theta \in (0, \pi) \\ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} & \text{if } \theta \in (\pi, 2\pi) \end{cases} = \begin{cases} + & \text{if } \theta \in (0, \pi) \\ - & \text{if } \theta \in (\pi, 2\pi) \end{cases}$

e.g. $\hat{n}_G = \frac{\det \begin{pmatrix} \frac{\partial x}{\partial u_1} & \frac{\partial x}{\partial u_2} \\ \frac{\partial y}{\partial u_1} & \frac{\partial y}{\partial u_2} \\ \frac{\partial z}{\partial u_1} & \frac{\partial z}{\partial u_2} \end{pmatrix}}{\left| \det \begin{pmatrix} \frac{\partial x}{\partial u_1} & \frac{\partial x}{\partial u_2} \\ \frac{\partial y}{\partial u_1} & \frac{\partial y}{\partial u_2} \\ \frac{\partial z}{\partial u_1} & \frac{\partial z}{\partial u_2} \end{pmatrix} \right|} \hat{n}_F$

overlap: $\det D(F_+^{-1} \circ F_-) < 0$

$\tilde{F}_-(x, y) := \tilde{F}_-(y, x)$

$\det D(F_+^{-1} \circ \tilde{F}_-) > 0$

$\mathbb{R}e^{i\theta} \mapsto \frac{1}{r} e^{i\theta}$

$F(\theta, z) = (\cos \theta, \sin \theta, z): (0, 2\pi) \times \mathbb{R} \rightarrow \text{Cylinder}$

$\tilde{F}(\theta, z) = (\cos \theta, \sin \theta, z): (-\pi, \pi) \times \mathbb{R} \rightarrow \text{Cylinder}$

$\tilde{F}^{-1} \circ F(\theta, z) = \begin{cases} (\theta, z) & \text{if } \theta \in (0, \pi) \\ (\theta - 2\pi, z) & \text{if } \theta \in (\pi, 2\pi) \end{cases}$

e.g. $\mathbb{R}P^2 = \{(x_1, x_2, x_3) : x_i \text{ not all zero}\}$

$F_0: (x_1, x_2) \mapsto [x_1 : x_2 : 1]$

$F_1: (y_0, y_1) \mapsto [y_0 : 1 : y_1]$

$\nexists F_0(x_1, x_2) = F_1(y_0, y_1) \Rightarrow [x_1 : x_2 : 1] = [y_0 : 1 : y_1]$

Domain $F_1^{-1} \circ F_0: \{x_1 \neq 0\}$

$y_0 = \frac{1}{x_1}, y_1 = \frac{x_2}{x_1} \Rightarrow \frac{\partial(y_0, y_1)}{\partial(x_1, x_2)} = \begin{bmatrix} -\frac{1}{x_1^2} & 0 \\ -\frac{x_2}{x_1^2} & \frac{1}{x_1} \end{bmatrix} \begin{matrix} y_0 \\ y_1 \end{matrix} = -\frac{1}{x_1^3}$

Prop: M^n orientable $\Leftrightarrow \exists$ non-vanishing n -form Ω .

Proof why $\mathbb{R}P^2$ is non-orientable:

Assume $\mathbb{R}P^2$ is orientable $\Rightarrow \exists \Omega$ 2-form on $\mathbb{R}P^2$ s.t. $\Omega(p) \neq 0 \quad \forall p \in \mathbb{R}P^2$.

Let $\Omega = f dx^1 \wedge dx^2$

$\Omega(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}) = f \begin{vmatrix} \frac{\partial x_1}{\partial y_0} & \frac{\partial x_2}{\partial y_0} \\ \frac{\partial x_1}{\partial y_1} & \frac{\partial x_2}{\partial y_1} \end{vmatrix} = f \begin{vmatrix} \frac{\partial x_1}{\partial y_0} & \frac{\partial x_2}{\partial y_0} \\ \frac{\partial x_1}{\partial y_1} & \frac{\partial x_2}{\partial y_1} \end{vmatrix} = f \det \begin{pmatrix} \frac{\partial x_1}{\partial y_0} & \frac{\partial x_2}{\partial y_0} \\ \frac{\partial x_1}{\partial y_1} & \frac{\partial x_2}{\partial y_1} \end{pmatrix}$

$\Omega = f \det \begin{pmatrix} \frac{\partial x_1}{\partial y_0} & \frac{\partial x_2}{\partial y_0} \\ \frac{\partial x_1}{\partial y_1} & \frac{\partial x_2}{\partial y_1} \end{pmatrix} dy^0 \wedge dy^1$

$g \cdot f \det > 0$, $g \cdot f \det < 0$

$\mathbb{R}^2: M$ can be covered by one parametrisation.

$F(u_1, \dots, u_n): U \rightarrow M$

$\Omega = f du^1 \wedge \dots \wedge du^n$

$\int_M \Omega := \int_U f du^1 \wedge \dots \wedge du^n$ (basically)

$\int_M f du^1 \wedge \dots \wedge du^n$ multivariable calculus integration.

Issue: $\int dx \wedge dy = -\int dy \wedge dx$

$\int_M f dx \wedge dy := \int_{\mathbb{R}^2} f dx dy$

$\int_M -f dy \wedge dx = \int_{\mathbb{R}^2} -f dy dx$

Pick: (x, y) as the order

then $\int_M x^2 y dy \wedge dx = \int_{\mathbb{R}^2} x^2 y dy dx \leftarrow (1, 0, 3, 3)$

$= \int_{\mathbb{R}^2} -x^2 y dx dy \leftarrow (2, 0, 7, 3)$

2^0 : Independent of coordinates?

$F(u_1, \dots, u_n): U \rightarrow M$

$G(v_1, \dots, v_n): V \rightarrow M$

Declare (u_1, \dots, u_n) as the order

$f du^1 \wedge \dots \wedge du^n = g dv^1 \wedge \dots \wedge dv^n$

Q: $\int f du^1 \wedge \dots \wedge du^n \stackrel{?}{=} \int g dv^1 \wedge \dots \wedge dv^n$

$f du^1 \wedge \dots \wedge du^n = f \det \begin{pmatrix} \frac{\partial u_1}{\partial v_1} & \dots & \frac{\partial u_1}{\partial v_n} \\ \dots & \dots & \dots \\ \frac{\partial u_n}{\partial v_1} & \dots & \frac{\partial u_n}{\partial v_n} \end{pmatrix} dv^1 \wedge \dots \wedge dv^n$

$\int g dv^1 \wedge \dots \wedge dv^n = \int f \det \begin{pmatrix} \frac{\partial u_1}{\partial v_1} & \dots & \frac{\partial u_1}{\partial v_n} \\ \dots & \dots & \dots \\ \frac{\partial u_n}{\partial v_1} & \dots & \frac{\partial u_n}{\partial v_n} \end{pmatrix} dv^1 \wedge \dots \wedge dv^n$ Need: (v_1, \dots, v_n) is the order of integration.

Need: $\det \begin{pmatrix} \frac{\partial u_1}{\partial v_1} & \dots & \frac{\partial u_1}{\partial v_n} \\ \dots & \dots & \dots \\ \frac{\partial u_n}{\partial v_1} & \dots & \frac{\partial u_n}{\partial v_n} \end{pmatrix} > 0 = + \int f du^1 \wedge \dots \wedge du^n = + \int f du^1 \wedge \dots \wedge du^n$

from 2023: $\int f \left| \det \begin{pmatrix} \frac{\partial u_1}{\partial v_1} & \dots & \frac{\partial u_1}{\partial v_n} \\ \dots & \dots & \dots \\ \frac{\partial u_n}{\partial v_1} & \dots & \frac{\partial u_n}{\partial v_n} \end{pmatrix} \right| dv^1 \wedge \dots \wedge dv^n = \int f du^1 \wedge \dots \wedge du^n$

S^2 covered by one parametrisation a.e.

e.g. $\omega = (i^* dx \wedge dy)$ $S^2 \subset \mathbb{R}^3$

$i^* dx = \frac{\partial x}{\partial \theta} d\theta + \frac{\partial x}{\partial \varphi} d\varphi = \cos \varphi \cos \theta d\theta - \sin \varphi \sin \theta d\varphi$

$i^* dy = -\sin \varphi \cos \theta d\theta - \cos \varphi \sin \theta d\varphi$

$\omega = (i^* dx) \wedge (i^* dy) = \sin \varphi \cos^2 \theta d\theta \wedge d\varphi$

$\int_{S^2} \omega = \int \omega = \int \sin \varphi \cos^2 \theta d\theta \wedge d\varphi = \int_0^{2\pi} \int_0^\pi \sin \varphi \cos^2 \theta d\varphi d\theta$

$= 0$



$\text{supp}(f) := \{x: f(x) \neq 0\}$

$\text{supp}(\omega) := \{p \in M: \omega(p) \neq 0\}$

If $U \cap \text{supp}(\omega) = \emptyset$

$\int_U \omega = 0$

If $U \cap \text{supp}(f) = \emptyset$ then $f \equiv 0$ on U . $f^{(m)} \equiv 0$ on U .

$\int_U f dx = 0$

Partition of unity (Def. 4.18, P.124)

$\mathcal{A} = \{F_\alpha: U_\alpha \rightarrow M\}$ atlas of M .

$\{p_\alpha: M \rightarrow [0, 1]\}$ is a partition of unity subordinate to \mathcal{A}

if

- $\text{supp}(p_\alpha) \subset F_\alpha(U_\alpha)$
- $\text{supp}(p_\alpha) \cap \text{supp}(p_\beta) = \emptyset$
- $\sum_{\text{all } \alpha} p_\alpha \equiv 1$ on M

$\omega = \left(\sum_{\text{all } \alpha} p_\alpha \right) \omega = \sum_{\text{all } \alpha} (p_\alpha \omega)$

$\int_M \omega = \sum_{\text{all } \alpha} \int_M (p_\alpha \omega)$

If $\exists \{U_\alpha: M \rightarrow [0, \infty)\}$ s.t. $\text{supp } U_\alpha \subset F_\alpha(U_\alpha) \quad \forall \alpha$ and $\forall p \in M, \exists \beta$ s.t. $U_\beta(p) \neq 0$.

then define: $p_\alpha := \frac{U_\alpha}{\sum_{\text{all } \alpha} U_\alpha}$

$\int_M \omega = \sum_\alpha \int_{F_\alpha(U_\alpha)} p_\alpha \omega$ is indep. of atlas, and indep. of the choice of p_α .

$\mathcal{A} = \{F_\alpha: U_\alpha \rightarrow M\} \leftarrow \{p_\alpha: M \rightarrow [0, 1]\}$

$\mathcal{A}' = \{G_\beta: V_\beta \rightarrow M\} \leftarrow \{q_\beta: M \rightarrow [0, 1]\}$

WANT: $\sum_\alpha \int_{F_\alpha(U_\alpha)} p_\alpha \omega = \sum_\beta \int_{G_\beta(V_\beta)} q_\beta \omega$

$\sum_\alpha \int_{F_\alpha(U_\alpha)} p_\alpha \omega = \sum_\alpha \int_{F_\alpha(U_\alpha)} \left(\sum_\beta \sigma_\beta \right) p_\alpha \omega = \sum_\alpha \sum_\beta \int_{F_\alpha(U_\alpha)} \sigma_\beta p_\alpha \omega$

$\sum_\beta \int_{G_\beta(V_\beta)} q_\beta \omega = \sum_\beta \int_{G_\beta(V_\beta)} \sigma_\beta \omega$

$\sum_\alpha \sum_\beta \int_{F_\alpha(U_\alpha) \cap G_\beta(V_\beta)} \sigma_\beta p_\alpha \omega = \sum_\beta \int_{G_\beta(V_\beta)} \sigma_\beta \omega$

For non-compact manifold, just assume $\text{supp}(\omega)$ is compact.

$\sum_\alpha \int_{F_\alpha(U_\alpha)} p_\alpha \omega$

M is orientable $\Leftrightarrow \exists$ an oriented atlas $\{F_\alpha: U_\alpha \rightarrow M\}$ s.t. $\det D(F_\alpha \circ F_\beta) > 0 \quad \forall \alpha, \beta$ on the overlap.

Prop. 4.25 $\Leftrightarrow \exists$ a non-vanishing n -form Ω on M (where $n = \dim M$).

$\forall p \in M, \Omega(p) \neq 0$

Proof: $\{p_\alpha: M \rightarrow [0, 1]\}$ partition of unity subordinate to \mathcal{A} .

$F_\alpha(u_1^1, \dots, u_n^1)$ local coordinates

$\eta_\alpha = du_1^1 \wedge \dots \wedge du_n^1 \neq 0$ on $F_\alpha(U_\alpha)$

Justify: $\forall p \in M, \Omega(p) \neq 0$.

$\Omega := \sum_\alpha p_\alpha \eta_\alpha$

$\eta_\beta = du_1^2 \wedge \dots \wedge du_n^2 = \det \begin{pmatrix} \frac{\partial u_1^2}{\partial u_1^1} & \dots & \frac{\partial u_1^2}{\partial u_n^1} \\ \dots & \dots & \dots \\ \frac{\partial u_n^2}{\partial u_1^1} & \dots & \frac{\partial u_n^2}{\partial u_n^1} \end{pmatrix} du_1^1 \wedge \dots \wedge du_n^1$

$\Omega(p) = \sum_\alpha p_\alpha \eta_\alpha(p) = \sum_\alpha p_\alpha \det \begin{pmatrix} \frac{\partial u_1^2}{\partial u_1^1} & \dots & \frac{\partial u_1^2}{\partial u_n^1} \\ \dots & \dots & \dots \\ \frac{\partial u_n^2}{\partial u_1^1} & \dots & \frac{\partial u_n^2}{\partial u_n^1} \end{pmatrix} du_1^1 \wedge \dots \wedge du_n^1$

$\exists \beta$ s.t. $p_\beta(p) > 0$.