

Chapter 3: $\otimes$ and $\wedge$

V = finite-dim. vector space over $\mathbb{R}$.
 $= \text{span}\{e_1, \dots, e_n\}$
basis.

V^* = set of all linear maps $f: V \rightarrow \mathbb{R}$.

eg. $V = \mathbb{R}^n$
 $f(x_1, \dots, x_n) = x_1, \dots, f \in V^*$
 $f(x_1, \dots, x_n) = x_1 + \dots + x_n, f \in V^*$
eg. $V = C[0,1]$. (dim = ∞)
 $I(f) = \int_0^1 f(x) dx, I \in C[0,1]^*$

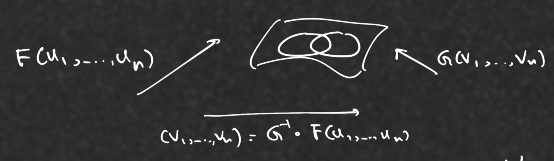
$g \in C[0,1]$ fixed. $J(f) = \int_0^1 f(x)g(x) dx, J \in C[0,1]^*$

V basis $\{e_1, \dots, e_n\}$.
 $e_i^* \in V^*, e_i^*(e_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$
 $e_2^*(e_1) = 0, e_2^*(e_2) = 1$
 $e_2^*(6e_1 + 8e_2 + 9e_3) = 8$

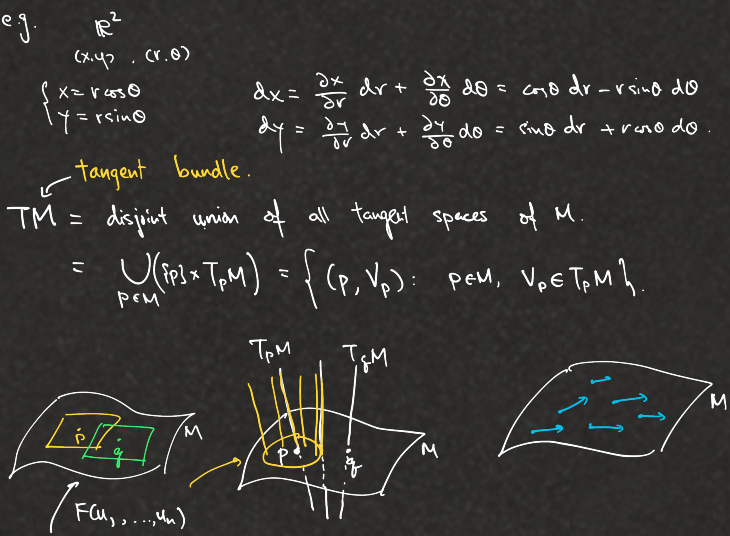
$\{e_1^*, e_2^*, \dots, e_n^*\}$ is a basis for V^* . (Exercise)
dual basis for V^* .

$T_p M = \text{span}\{\frac{\partial}{\partial x_1}|_p, \dots, \frac{\partial}{\partial x_n}|_p\}$
 $T_p^* M =$ dual space of $T_p M$.
 $\wedge$ cotangent space at $p \in M$.
 $T_p^* M = \text{span}\{\underbrace{du^1|_p, \dots, du^n|_p}_{\text{dual basis}}\}$

eg. $\mathbb{R}^4(t, x, y, z)$
 $\frac{\partial}{\partial t}, \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}$
 $dt(\frac{\partial}{\partial t}) = 1, dt(\frac{\partial}{\partial x}) = 0, \dots$



$\frac{\partial}{\partial u_i} = \sum_j \frac{\partial u_j}{\partial u_i} \frac{\partial}{\partial u_j}$ ✓
 $du^i(\frac{\partial}{\partial u_j}) = \delta_{ij}$
 $du^i = \sum_j \frac{\partial u_i}{\partial u_j} du^j$
eg. $\mathbb{R}^2$ (x,y), (r,θ)
 $x = r \cos \theta, y = r \sin \theta$
 $dx = \frac{\partial x}{\partial r} dr + \frac{\partial x}{\partial \theta} d\theta = \cos \theta dr - r \sin \theta d\theta$
 $dy = \frac{\partial y}{\partial r} dr + \frac{\partial y}{\partial \theta} d\theta = \sin \theta dr + r \cos \theta d\theta$

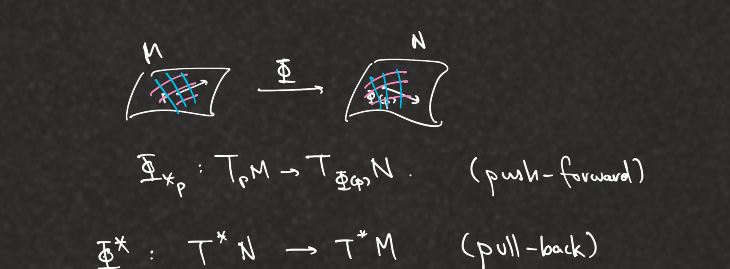


$\tilde{F}(u_1, \dots, u_n, a^1, \dots, a^n) = (F(u_1, \dots, u_n), a^1 \frac{\partial}{\partial u_1} + \dots + a^n \frac{\partial}{\partial u_n})$
TM is a smooth 2n-manifold.
V is a vector field on M.
 $\frac{dF}{dt}: V: M \rightarrow TM$ and $V(p) \in \mathbb{R}p \times T_p M$ b/p.m.
V is a C^k (or C^∞) vector field on M $\xrightarrow{\text{def}}$ $V: M \rightarrow TM$ is C^k (or C^∞).
 $\tilde{F}^{-1} \circ V \circ F$ is C^k (or C^∞) $\iff a^i(u_1, \dots, u_n)$ are C^k (C^∞)
 $\tilde{F}^{-1} \circ V \circ F(u_1, \dots, u_n) = \tilde{F}^{-1}(F(u_1, \dots, u_n), \sum_{i=1}^n a^i \frac{\partial}{\partial u_i}) = (u_1, \dots, u_n, a^1, \dots, a^n)$
eg. $V = (x^2 + y^2) \frac{\partial}{\partial x} + (y^2 + x^2) \frac{\partial}{\partial y}$ ($\mathbb{R}^2$)
 $W = \sqrt{x^2 + y^2} \frac{\partial}{\partial x} + (x^2 + y^2)^{3/2} \frac{\partial}{\partial y}$ not C^1 .

$du^i(\frac{\partial}{\partial u_j}) = \delta_{ij}$
 $\sum_i a_i du^i$

$TM = \bigcup_{p \in M} \mathbb{R}p \times T_p^* M$
 $= \{(p, \omega_p) : p \in M, \omega_p \in T_p^* M\}$
Check: TM is a smooth 2n-manifold
 $\dim M = n$.

$\omega: M \rightarrow TM \leftarrow$
 $\omega(p) \in \mathbb{R}p \times T_p^* M$
 ω : differential 1-form.
If $\omega: M \rightarrow TM$ is C^k (or C^∞), then call it C^k (or C^∞) differential 1-form.
 $\omega(F(u_1, \dots, u_n)) = (F(u_1, \dots, u_n), \sum_{i=1}^n a_i(u_1, \dots, u_n) du^i)$



$\Phi^*: T^* N \rightarrow T^* M$ (pull-back)
 $\Phi^*(\omega) : TM \rightarrow \mathbb{R}$
in $T^* N$ in TM in $T^* M$
 $(\Phi^*(\omega))(V) := \omega(\Phi_*(V))$
in TM in TN in TM

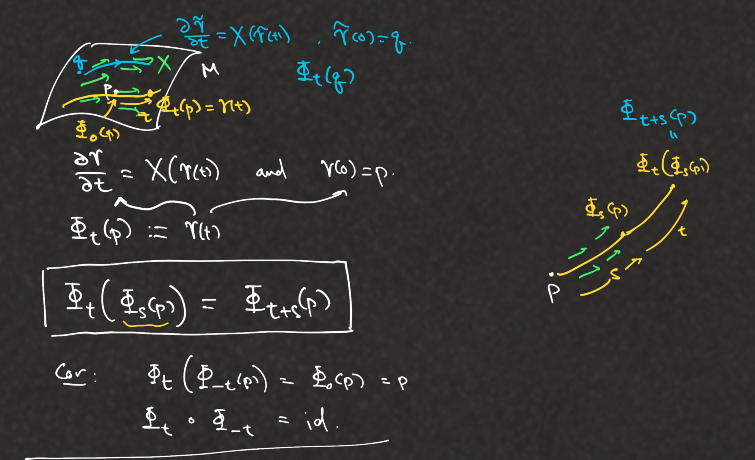
eg. $\Phi: \mathbb{R} \rightarrow \mathbb{R}^2 \setminus \{0\}$
 $\Phi(t) := (\cos t, \sin t)$
 $TR = 4\pi m(\frac{\partial}{\partial t})$
 $\omega = -\frac{y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$
 $\frac{\partial \Phi}{\partial t} = -\sin t \frac{\partial}{\partial x} + \cos t \frac{\partial}{\partial y}$
 $(\Phi^*(\omega))(\frac{\partial}{\partial t}) = \omega(\Phi_*(\frac{\partial}{\partial t}))$
 $= \omega(-\sin t \frac{\partial}{\partial x} + \cos t \frac{\partial}{\partial y}) = (-\frac{y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy)(-\sin t \frac{\partial}{\partial x} + \cos t \frac{\partial}{\partial y})$
 $= \frac{y \sin t}{x^2+y^2} + \frac{x \cos t}{x^2+y^2} = 1 \Rightarrow \Phi^* \omega = dt$

eg. $\Sigma^2 \subset \mathbb{R}^3$ (x,y,z) regular surface.
 $L: \Sigma \rightarrow \mathbb{R}^3$ inclusion
 $P \mapsto P$
 $(L^* dx)(\frac{\partial}{\partial u}) = dx(L_*(\frac{\partial}{\partial u})) = dx(\frac{\partial x}{\partial u} \frac{\partial}{\partial x} + \frac{\partial y}{\partial u} \frac{\partial}{\partial y} + \frac{\partial z}{\partial u} \frac{\partial}{\partial z})$
 $= \frac{\partial x}{\partial u}$
 $(L^* dx)(\frac{\partial}{\partial v}) = \frac{\partial x}{\partial v}$
 $\Rightarrow L^* dx = \frac{\partial x}{\partial u} du + \frac{\partial x}{\partial v} dv$

$M \xrightarrow{\Phi} N$
 $F \uparrow \quad \quad \uparrow G$
 $(u_1, \dots, u_m) \xrightarrow{G \circ F} (v_1, \dots, v_n)$
 $(v_1, \dots, v_n) = G^{-1} \circ \Phi \circ F(u_1, \dots, u_m)$
 $(\Phi^* du^i)(\frac{\partial}{\partial u_j}) = du^i(\Phi_*(\frac{\partial}{\partial u_j}))$
 $= du^i(\frac{\partial x}{\partial u_j}) = \frac{\partial x}{\partial u_j}$
 $= du^i(\frac{\partial v_1}{\partial u_j} \frac{\partial}{\partial v_1} + \dots + \frac{\partial v_n}{\partial u_j} \frac{\partial}{\partial v_n})$
 $= \frac{\partial v_i}{\partial u_j}$
 $\Rightarrow \Phi^* du^i = \sum_{j=1}^n \frac{\partial v_i}{\partial u_j} du^j$
 $[\Phi^*] = \begin{bmatrix} \Phi^* du^1 & \dots & \Phi^* du^n \end{bmatrix}^T = \begin{bmatrix} \frac{\partial v_1}{\partial u_1} & \dots & \frac{\partial v_1}{\partial u_m} \\ \vdots & \ddots & \vdots \\ \frac{\partial v_n}{\partial u_1} & \dots & \frac{\partial v_n}{\partial u_m} \end{bmatrix}^T = \left(\frac{\partial (v_1, \dots, v_n)}{\partial (u_1, \dots, u_m)} \right)^T$
 $(\Phi \circ \psi)^* = \psi^* \circ \Phi^*$
 $|\psi\rangle \quad \langle \psi| \quad |\psi\rangle = \sum_i \langle e_i | \psi \rangle |e_i\rangle$
 $\langle \psi| = \sum_i \langle \psi | e_i \rangle \langle e_i|$
 $T = \sum_i T(e_i) e_i^*$

Lie derivatives
In $\mathbb{R}^n$.
 $\gamma(t) : (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n$
 $\gamma: \mathbb{R}^n \rightarrow \mathbb{R}^n, f: \mathbb{R}^n \rightarrow \mathbb{R}$
 $D_{\gamma(t)} \gamma = \frac{d}{dt} \gamma \circ \gamma = \frac{d}{dt} f \circ \gamma$
 $= \lim_{h \rightarrow 0} \frac{\gamma(\gamma(t+h)) - \gamma(t)}{h}$

$(D_X \gamma)_p = (D_{\gamma(t)} \gamma)_p$
If X is C^1 on $\mathbb{R}^n$ then given any $p \in \mathbb{R}^n$ $\exists \gamma: I \rightarrow \mathbb{R}^n$ s.t. $\gamma'(t) = X(\gamma(t))$ and $\gamma(0) = p$. (existence theorem of ODE).
 $(D_X \gamma)_p = (D_{\gamma(t)} \gamma)_p$



$(\mathcal{L}_X Y)_p = \frac{d}{dt} \Big|_{t=0} (\Phi_{-t})_* (Y_{\Phi_t(p)})$
 $X(Y(f)) - Y(X(f)) = [X, Y]f$
 $[X, Y] = XY - YX$
 $X = \sum_i X^i \frac{\partial}{\partial x_i}, Y = \sum_j Y^j \frac{\partial}{\partial x_j}$
 $X(Y(f)) = \sum_i X^i \frac{\partial}{\partial x_i} (\sum_j Y^j \frac{\partial f}{\partial x_j}) = \sum_{i,j} X^i (\frac{\partial Y^j}{\partial x_i} \frac{\partial f}{\partial x_j} + Y^j \frac{\partial^2 f}{\partial x_i \partial x_j})$
 $Y(X(f)) = \sum_j Y^j \frac{\partial}{\partial x_j} (\sum_i X^i \frac{\partial f}{\partial x_i}) = \sum_{i,j} Y^j (\frac{\partial X^i}{\partial x_j} \frac{\partial f}{\partial x_i} + X^i \frac{\partial^2 f}{\partial x_j \partial x_i})$
 $[X, Y]f = \sum_{i,j} (X^i \frac{\partial Y^j}{\partial x_i} - Y^j \frac{\partial X^i}{\partial x_j}) \frac{\partial f}{\partial x_j}$
 $[\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}] = 0$

Prop. 3.23 $\mathcal{L}_X Y = [X, Y]$ where X, Y are vector fields.
 $X(Y(f)) - Y(X(f)) = [X, Y]f$
 $[X, Y] = XY - YX$

Sketch of proof of $\mathcal{L}_X Y = [X, Y]$.
 $(\mathcal{L}_X Y)_p = \frac{d}{dt} \Big|_{t=0} (\Phi_{-t})_* (Y_{\Phi_t(p)})$
 $F^{-1} \circ \Phi_{-t} \circ F(u_1, \dots, u_m) = (v_1^t, \dots, v_m^t)$
 $\frac{\partial \Phi_t}{\partial t} = \sum_i \frac{\partial v_i^t}{\partial t} \frac{\partial}{\partial v_i^t} = \sum_i \frac{\partial v_i^t}{\partial t} \frac{\partial}{\partial u_i}$
 $\sum_i X^i \frac{\partial}{\partial x_i} = \sum_i Y^i \frac{\partial}{\partial x_i}$
 $(\Phi_{-t})_* (Y_{\Phi_t(p)}) = (\Phi_{-t})_* (\sum_j Y^j \frac{\partial}{\partial x_j})$
 $= \sum_j Y^j \frac{\partial (\Phi_{-t})}{\partial x_j}$
 $= \sum_j Y^j (\sum_i \frac{\partial v_i^t}{\partial x_j} \frac{\partial}{\partial v_i^t})$
Next: $\frac{d}{dt} \Big|_{t=0} (\Phi_{-t})_* (Y_{\Phi_t(p)}) = \dots$

$(\mathcal{L}_X Y)_p = \frac{d}{dt} \Big|_{t=0} (\Phi_{-t})_* (Y_{\Phi_t(p)}) \stackrel{\text{prop}}{=} [X, Y]_p$
If $[X, Y] \equiv 0$, then $(\Phi_{-t})_* (Y_{\Phi_t(p)}) = (\Phi_0)_* (Y_{\Phi_0(p)}) = Y_p$
 $\Rightarrow (\Phi_t)_* ((\Phi_{-t})_* (Y_{\Phi_t(p)})) = (\Phi_t)_* Y_p$
 $Y_{\Phi_t(p)} = (\Phi_t)_* Y_p$

$\frac{\partial \Phi_t(p)}{\partial t} = X(\Phi_t(p))$
 $\frac{\partial \psi_s(p)}{\partial s} = Y(\psi_s(p))$
If $[X, Y] \equiv 0$, then $\Phi_t \circ \psi_s = \psi_s \circ \Phi_t$.
Prop. $\frac{\partial}{\partial t} (\Phi_t \circ \psi_s)(p) = \frac{\partial}{\partial t} \Phi_t(\psi_s(p)) = X(\Phi_t(\psi_s(p)))$
 $\frac{\partial}{\partial t} (\psi_s \circ \Phi_t)(p) = \dots = X(\psi_s(\Phi_t(p)))$

$F(s, t) := \Phi_t \circ \psi_s(p) = \gamma_s \circ \Phi_t(p)$
 $\frac{\partial F}{\partial s} = Y$
 $\frac{\partial F}{\partial t} = X$
 $\frac{d}{dt} \Big|_{t=0} \frac{\partial F}{\partial s} = \mathcal{L}_X Y$
 $\frac{d}{dt} \Big|_{t=0} \frac{\partial F}{\partial t} = \mathcal{L}_Y X$
 $\mathcal{L}_X Y = [X, Y]$

$\frac{d}{dt} \Big|_{t=0} \frac{\partial F}{\partial s} = \mathcal{L}_X Y$
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